

Making an Accurate Acupuncture Feedback Platform in Virtual Teaching Environment

By Boyu Xu

The Glasgow School of Art School of Simulation and Visualisation MSc in Serious Games and Virtual Reality Supervisor: Dr. Matthieu Poyade August 18, 2018

Abstract

Acupuncture can be an ancient art in the traditional Chinese medicine. It is difficult to teach and train for the young generation, but in recent years, there has been an increased interest in using interacted methods to enhance educational settings, especially with a growing focus on Virtual Reality(VR).

The purpose of this project is to develop and test an accurate acupuncture feedback platform in the virtual environment with immersing Virtual Reality(VR) and integrated haptics for the teaching and training in the early stage of acupuncture learning and explore a vivid and visual method to deliver the technologies of acupuncture to the young generation.

An introduction interface and the interacted methods are combined with the Virtual Reality(VR) and haptic technologies to establish concurrent and terminal feedback platform. To evaluate the interactive application, the study was conducted with ten participants who were students from GSA and the professional acupuncturists in the UK. Participants implemented feedback questionnaires at the end of testing. The overall feedback received was positive. Also, the acupuncturists took part in the calibration of the needling feedback. Due to the positive feedback, further developments could be refined on the feedback training.

Acknowledgement

I would like to show my appreciation to everyone who helped e through this process.

Firstly, I would like to thank my supervisors, Dr. Matthieu Poyade for his valuable help and contributions during my project. His passion for this area of study provided strong motivation to keep pushing myself to implement a better work.

Furthermore, thanks to Loranger Brian for scripting support through the process of developing this application, and thanks to Yin Gu who provided the modeling support on the initial prototype of the application. I feel the time that was saved with Brian's guidance helped me to integrate all functions into the final application.

Finally, I would like to thank Yifeng Wu and Zi Mu for dubbing in the project and all the participants that were involved in testing and providing feedback for the application. I would also like to thank the two professional acupuncturists for sharing their knowledge and experience throughout the testing, which helped me improve the accuracy of feedback in the application.

Table of Contents

Abstract	2
Acknowledgement	3
List of Tables	6
List of Figures	8
Declaration of Originality	11
Definitions and Abbreviations	12
1 Introduction	14
1.1 Rationale	14
1.2 Aims	15
1.3 Hypothesis	16
1.4 Structure of Thesis	17
2 Literature Review	18
2.1 Introduction	18
2.2 Teaching and learning acupuncture	19
2.2.1 Acupuncture Theory	19
2.2.2 Learning Tools in Acupuncture	21
2.2.2.1 Traditional Learning Tools	21
2.2.2.2 Modern Learning Methods	21
2.3 Virtual Reality	22
2.3.1 Description of Virtual Reality	22
2.3.1.1 Definition of Virtual Reality	22
2.3.1.2 Features of Virtual Reality	23
2.3.2 Virtual Reality in Medical Education	24
2.4 Haptic Technology	24
2.4.1 Haptic Device	24
2.4.2 Haptic Technology in Medical Education	27
2.5 Virtual Simulation and Integrated in Acupuncture	27
3 Materials and Methods	31
3.1 Materials	31
3.1.1 Medical Image Information and models	31
3.1.2 Hardware	33
3.1.2.3.1 The information of Phantom Omni	37
3.1.2.3.2 Six Degrees of Freedom (6DoF) in Phantom Omni	39
3.1.3 Software	39
3.2 Methods	41

	3.2.1 Requirement Analysis	42
	3.2.2 Design and Development	54
	3.2.2.1 Storyboard of Application	54
	3.2.2.2 Storyboard of Introduction Interface	58
	3.2.3 Creating Context and Assets	60
	3.2.3.1 3D Modelling	
	3.2.3.2 Introduction Animation	
	3.2.4 Configuration for the Application	
	3.2.5 VR Environment 3.2.5.1 Programming of the Application in Virtual Environment	
	3.2.6 Haptic Interaction	
	3.2.6.1 Programming of the Application in Haptic Interaction	
	3.2.6.2 Implementing the Feedback Platform Prototype	
	3.2.7 Final Design of the Application - Combining VR and Haptic tech	nology
4	Results	89
	4.1 Introduction Animation	89
	4.2 Application Results	92
	4.2.1 Start and Introduction	92
	4.2.2 Accurate Needling Training	94
	4.2.3 Terminal Needling Results	99
	4.2.4 Acupuncture and Anatomy Learning	102
	4.2.5 Languages System	103
5	Evaluation	105
	5.1 Introduction	105
	5.2 Methods	105
	5.2.1 Participants	105
	5.2.2 Experimental Set-up	106
	5.2.3 Procedures	106
	5.2.3.1 Testing by the Professional Acupuncturist	106
	5.2.3.2 Testing by the GSA Students	107
	5.2.3.3 Data Analysis	107
	5.3 Results	
	5.3.1 Calibration	108
	5.3.2 Questionnaire Outcomes and Data Analysis	
	5.3.3 Results of Evaluation	
	5.4 Conclusion of Evaluation	
6	Discussions and Conclusion	
5	6.1 Discussions	

6.1.1 Discussion of Development Process	119
6.1.2 Discussion of Immersion	119
6.1.3 Discussion of Potential for Learning	120
6.2 Limitations	121
6.3 Conclusion	122
6.4 Future Development	123
Reference	124
Appendix 1 - Questionnaires	128
Appendix 2 - Introduction Video	137

List of Tables

Table 1-1 Flowchart of the structure of the thesis	17
Table 3-1 Illustrating the information of image and reference	32
Table 3- 2 Illustrating the information of models and reference	33
Table 3-3 listing the specific requirements of the computer in the project	34
Table 3-3-1 The minimum requirement for the computer to run application	34
Table 3-3-2 The configuration of the computer to show the demo in GSA	35
Table 3-4 the detailed description of HTC Vive	36
Table 3-5 The detailed description of Phantom Omni	38
Table 3-6 the Six Degrees of Freedom (6DoF) in the haptic device	39
Table 3-7 List of software used for the application, including a description of their	
use	40
Table 3-8 Flowchart of the design process for the application	41
Table 3-9 Requirement Diagram	42
Table 3-9-1 Table for the Application Requirements	43
Table 3-9-2 Illustrating the information of models and reference	73
Chart 5-1 The understanding of the concept about the acupuncture for students	109
Chart 5-2 The frequency of seeing the professional acupuncturist	109
Chart 5-3 The reliability of the acupuncture	110
Chart 5-4 Choose the acupuncture to treat the scapulohumeral periarthritis	110
Table 5-1 Different levels of comments about the understanding of acupuncture	
knowledge in the application	.111
Table 5-2 The data statistics for the understanding of the knowledge in acupunct	ure
from eight students	111
Chart 5-5 Mean value and error bars for questions testing the learning outcomes	
about the knowledge of acupuncture from eight students	112
Table 5-3 The data statistics for the understanding of the knowledge in acupunct	ure
from two acupuncturists	112
Chart 5-6 Mean value and error bars for questions testing the learning outcomes	
about the knowledge of acupuncture from two acupuncturists	113
Table 5-4 shows the number means different level of agreement	113
Table 5-5 The data analysis of the accurate feedback system	114
Chart 5-7 Mean value and error bars about the comments of needling feedback	
system	115

Table 5-6 The data statistics about the comments in the feeling of the virtual	
environment	115
Chart 5-8 Mean value and error bars about the comments of immersion and	
visualization	115
Table 5-7 The data statistics about the comments of the application	116
Chart 5-9 Mean value and error bars about the comments of the application	116

List of Figures

Figure 2-1 The Massachusetts General Hospital acupuncture sensation scales	
(MASS)	20
Figure 2-2 The haptic loop	26
Figure 2-3 Needle puncture on the acupoint Sanyinjiao	28
Figure 2-4 User interface and operation situation of the research	28
Figure 2-5 The changing of the force in haptic simulation for acupuncture	29
Figure 2-6 The simulator needling training situation	30
Figure 2-7 The Voxel-Man System	30
Figure: 3-1-1 Human anatomical image: Thorax	32
Figure: 3-1-2 Human anatomical image: Forearm	32
Figure 3-4-1 Headset	36
Figure 3-4-2 Controller	36
Figure 3-4-3 Base Stations	36
Figure 3-4-4 HTC Vive Playing Space	36
Figure 3-5-1 The modeling of Phantom Omni	38
Figure 3-10-1 The sketch of the start menu	54
Figure 3-10-2 The sketch of the introduction interface	55
Figure 3-10-3 The sketch of the acupuncture training interface	56
Figure 3-10-4 The sketch of the acupuncture training interface	57
Figure 3-10-5 The storyboard of the introduction of the periarthritis of shoulder	58
Figure 3-10-6 The storyboard of the professional acupuncture term	59
Figure 3-11-1 3D modeling - open resources in online ANATOMY MODELS STOR	E60
Figure 3-11-2 The original model	61
Figure 3-11-3 The changed model - using the translucent material on the skin	61
Figure 3-11-4 The whole model with the translucent material	62
Figure 3-11-5 Cut function	63
Figure 3-11-6 The cutting shoulder model	63
Figure 3-11-7 The cutting arm model	64
Figure 3-12-1 The process of designing the animation	65
Figure 3-12-2 The process of designing the animation	63
Figure 3-12-3 Transform the animation into Unity step by step	66
Figure 3-13-1 The room-scale to establish the virtual environment	67
Figure 3-13-2 The correct experience situation	68
Figure 3-14-1 Setting the headset and controllers	69

Figure 3-14-2 The vital points about establishing the Canvas in VR	.70
Figure 3-14-3 The function of the controller	70
Figure 3-14-4 Plugin - VR Toolkit	70
Figure 3-14-5 The scripting of button clicking	71
Figure 3-14-6 Arranging the scripting on the specific button	.72
Figure 3-15-1 The prototype of the application has four scenes	.72
Figure 3-15-2 Arranging the VR camera	
Figure 3-15- 3 Doctor's Office models	
Figure 3-15-4 The animation tip on the brown needle	
Figure 3-15-5 The animator on the brown needle	
Figure 3-15-6 The scripting to make many elements in the application run in order.	
Figure 3-16-1 shows "MygoodNeedle" in the environment	75
Figure 3-16-2 shows the excellent needle model has been connected with the hap	tic
device	.78
Figure 3-16-3 shows the moving space of the haptic device	
Figure 3-16-4 The scripting achieves the collision detection	.80
Figure 3-16-5 The function prototype of choosing the relative needle	80
Figure 3-16-6 shows the two buttons on the haptic device	80
Figure 3-16-7 shows the scripting about using the button to change the color	
Figure 3-16-8 shows the prototype of the choosing needles	
Figure 3-16-9 The process of creating the real-time feedback texture on Canvas	83
Figure 3-16-10 shows the size, type, and path of the saving texture	84
Figure 3-16-11 shows pressing the Button2 on the haptic device and then the textu	ıre
saved	.85
Figure 3-16-12 shows the scripting of loading the saved texture from the fixed path	1.85
Figure 3-16-13 shows the image on Canvas which shows the saved texture	.86
Figure 3-17-1 shows the concurrent feedback	.87
Figure 3-17-2 shows loading the saved texture on Canvas	87
Figure 3-17-3 shows the environment of the application in HTC Vive	88
Figure 3-17-4 shows the haptic development in the virtual environment	.88
Figure 4-1 The animation images about the introduction of the periarthritis of	
shoulder	.89
Figure 4-2 The introduction animation in VR	.90
Figure 4-3 The animation images about the introduction of the acupuncture	91
Figure 4-4 The start interface	.92
Figure 4-5 The introduction of the periarthritis of shoulder and the acupuncture	.92
Figure 4-6 Choosing a language to enter into the acupuncture training centre	91

Figure 4-7 The introduction of acupuncture training centre	94
Figure 4-8 The animation of the disease	94
Figure 4-9 The introduction of the disease	95
Figure 4-10 The hint animation of the acupoint	95
Figure 4-11 The choosing needle operation and feedback	96
Figure 4-12 The concurrent operation and feedback about the needling	97
Figure 4-13 The real-time judgment with the operation (right label)	98
Figure 4-14 The force chart of the needling	98
Figure 4-15 The terminal results are shown on the scoreboard	99
Figure 4-16 The correct needling and anatomical animation	100
Figure 4-17 The main meridian channels to remit the disease	101
Figure 4-18 Send the terminal images to the professional acupuncturist	101
Figure 4-19 The audio tip of the steps in the acupuncture training	102
Figure 4-19-1 The audio tip of the introduction of the acupoint	102
Figure 4- 20 The English System	103
Figure 4- 21 The Chinese System	105
Figure 5-1 The testing situation	106
Figure 5-2 The needling feedback force across the skin	108
Figure 5-3 The needling feedback force across the muscle	108

Declaration of Originality

STUDENT ID No.: ________

Own Work Declaration

You must complete this declaration (each box ticked to show that the condition has been met), signed and dated, and included with each piece of work submitted for assessment (practical and written). Please note work will not be accepted unless this from is attached.

As GSA have now obtained Turnitin plagiarism software, a cross section of student submissions will be evaluated.

Name:Boyu Xu.....

Course/Programme: ...MSc in Serious Games and Virtual Reality......

Title of Work: ...Making an accurate acupuncture feedback platform in virtual teaching environment.....

I confirm that all this work is my own except where indicated, and that I have:

· Clearly referenced/listed all sources as appropriate

• Referenced and added inverted commas to all quoted text (from books, journals, web, etc)

· Given the sources of all pictures, sound, data etc. that are not my own

• Not made any use of the report(s) or essay(s) of any other student(s) either past or present, or lifted extracts from web pages without appropriate referencing

• Not sought or used the help of any external professional agencies for the work

• Acknowledged in appropriate places any help that I have received from others (e.g. fellow students, technicians, statisticians, external sources)

· Complied with any other plagiarism criteria specified in the Course Handbook

I understand that any false claim for this work will be penalised in accordance with the GSA regulations

Signature: Date:18/08/2018.....

Definitions and Abbreviations

1. Acupuncture - Acupuncture is a part of Traditional Chinese Medicine, it can help patients to remit the disease by using suitable needles to penetrate accurate acupoints.

2. Acupoint - Acupoint is the specific point in the body, it is useful to remit the disease by needling acupoints.

3. The main and meridian channels - The main meridian channels are the vital constituent parts of the body. Needling can penetrate the acupoint, and generate the meridian channel to make patients feel comfortable.

- 4. AE Adobe After Effects
- 5. AI Adobe Illustrator
- 6. Flash Adobe Flash Professional
- 7. DoF Degrees of Freedom
- 8. VR Virtual Reality
- 9. App The acupuncture application

1 Introduction

Acupuncture is a difficult part of the Traditional Chinese Medicine to both teach and train, particularly transferring the knowledge about the process of operating the acupuncture to the young generation. A case of study which performed by Pheng-Ann Heng (2006) which reviews a haptic needle manipulation simulator for Chinese acupuncture learning and training. In addition, Yuchen Jiang (2016) explored the using of Virtual Reality technology in the training of acupuncture. However, there are still improvements to be made in the teaching and training of acupuncture. There are many studies which focus on the haptic feedback force of the needling, or the virtual body in the acupuncture. These studies only point out the Virtual Reality or haptic technology independently and the rationale and accurate training of acupuncture are obscure in these professional explorations, such as using the Virtual Reality of acupuncture alone in the digital virtual human (Jun, J., et al. 2016).

The study of making an accurate acupuncture feedback platform in virtual teaching environment aims to combine the Virtual Reality and the haptic technology to create a platform to deliver the rationale of acupuncture to the youth and provide the accurate real-time and terminal feedback in the needling training. Simulation is the vital requirement of VR technology, and the application has a strong development in the simulate and visual expression. Furthermore, the accurate feedback of acupuncture is achieved by the combining of haptic technology and VR.

1.1 Rationale

The effectiveness of VR and haptic technology in the learning and training of acupuncture and delivering the knowledge of acupuncture clearly to the young generation are the vital features of the application. The rationale for the study is shown below:

1. The application can make students understand the relationship between the anatomy and acupuncture, and train the needling repeatedly.

2. The haptic technology can make students "feel" the haptic characteristics of materials and the virtual environment helps them learn the anatomy and acupoint.

3. The using of VR and haptic technology in acupuncture can not only help learners learn about the operation of acupuncture, but also create a new teaching method to save the physical materials in the teaching of acupuncture.

4. These technologies can provide a natural way to teach and train the acupuncture, it also provides a preparation for students to needle the real tissues.5. The technologies of acupuncture can be delivered to the young generation clearly by the user-friendly introduction interface.

1.2 Aims

The aim of this research conducted is making an accurate acupuncture feedback platform in the process of teaching and training acupuncture, and exploring a modern method to deliver the knowledge of acupuncture to the youth better. The aim of the study is shown below:

1. Make the simulated and haptic teaching platform to improve the teaching and training method in the acupuncture field.

2. Develop an efficient information feedback strategy in the form of concurrent and terminal feedback to support the training and learning of acupuncture.

3. Deliver the rationale and knowledge of acupuncture to the young generation by the friendly and pellucid image information.

4. Provide repeated simulation for learning the relationship between the acupuncture and anatomy, and exercising the operation of acupuncture.

These aims will be achieved in a virtual acupuncture centre where the learners will learn the knowledge of acupuncture and perform the process of needling. Using Virtual Reality(VR) and haptic technology could make learners immerse in the operation environment, and get a real-time feedback step by step. Moreover, the learners could be free to interact in the virtual environment and achieve more effective learning results in the application. Finally, the learners could learn the rationale of acupuncture and the anatomic knowledge smoothly in the operation.

1.3 Hypothesis

The study will be useful for both learners of acupuncture and professional acupuncturists. The hypothesis for the study is shown below:

For the learner:

1. Learners with little acupuncture knowledge can learn the knowledge of acupuncture and anatomy in a friendly visual system.

2. Acupuncture knowledge can be delivered to the youth through modern imaging and interactions.

3. Through haptic feedback by haptic technology in virtual environments, learners are able to perform accurate acupuncture operations and understand the knowledge of acupuncture further.

4. Accurate concurrent and terminal feedback can help learners in understanding the needling, choose the needle and position acupoints.

5. Repeated training can help learners make a preparation for the future real acupuncture training.

For the professional acupuncturist:

1. Offer opportunities for professional acupuncturists to plan the acupuncture operation before the practical needling, through the Virtual Reality and haptic technology.

2. Help professional acupuncturists to know the disadvantage of needling using real-time and terminal feedback.

1.4 Structure of Thesis

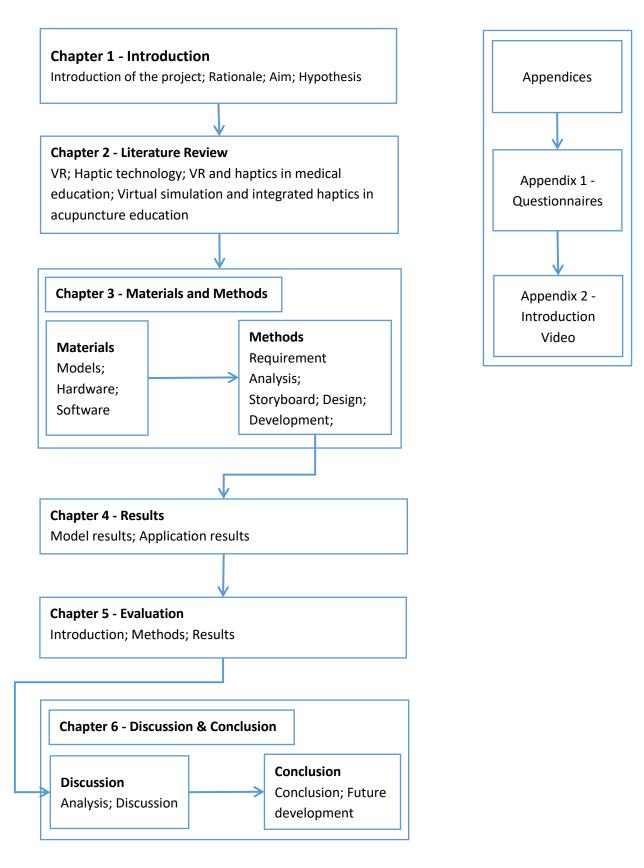


Table 1-1 Flowchart of the structure of the thesis.

2 Literature Review

2.1 Introduction

With the development of science and technology, the educational system must adapt to enhance traditional teaching methods with the blending of digital and virtual resources. There is a thesis to suggest that learning is an individual interacts with information and the environment through the development of new knowledge, skills or attitudes (SE Smaldino et al., 2004). Therefore, in the learning system, the interaction with the knowledge and environment is a vital point, and it could be particularly significant in the teaching and learning of acupuncture.

Although acupuncture has been used for thousands of years and is useful in a wide range of situation, the scientificity of acupuncture is a controversial issue (Tsuei J., 1996). However, with continuous study in acupuncture, the electrodermal screening test (EDST) and electrodermal screening device (EDSD) was put forward in 1996 (Tsuei J.J., 1996). It made the research of acupuncture combining with the solid theoretical foundation in modern physics and quantum mechanics. It meant people could understand acupuncture by actual numerical value. Besides, in 2006, students could learn and practice acupuncture in the advanced 3D interactive environment that supported by force feedback haptic and Virtual Reality technologies(Heng et al., 2006). It was the first attempt to develop a virtual human model for studying Chinese medicine (Heng et al., 2006). It was also achieving the experiential learning (Dewey, J., Lewin, K., 1984) in the teaching of acupuncture. Practice in virtual acupuncture environment could get hands-on learning.

Although current teaching methods in acupuncture have advanced a lot, some institutions are interested in paying more attention to creating better learning tool on acupuncture by different interactive ways, such as Virtual Reality and pen-force feedback tool.

2.2 Teaching and learning acupuncture

In this part, an introduction to the theory of acupuncture will be made, and the learning tools in the development of teaching in acupuncture will be illustrated.

2.2.1 Acupuncture Theory

In the traditional sense, naturalistic theories have the vital influence on the acupuncture, and the naturalistic theories are compatible with Confucianism and Taoism. Such ideas as yin-yang, qi, dampness, and wind represent East Asian conceptual frameworks that emphasize the reliability of ordinary, human sensory awareness are the cores of the acupuncture (J. Kaptchuk, 2002). In the traditional acupuncture treatment, the connection between acupuncture needles and the energy pathways of the body is described by De qi, which is an essential conventional measure standard of acupuncture treatment. The concept of De qi is discussed in the earliest Chinese medical texts, but the details phenomenon were fully described in the recent hundred years through the experiences between the acupuncturists and patients (Jian Kong et al., 2007).

In 2007, researchers reviewed the acupuncture field systematically and put forward a scale "MASS" to measure the feeling of patients when the needle penetrated the tissue of the body. Researchers hoped their efforts would enhance the rigor of acupuncture, and they introduced "Mass" to measure De qi (Jian Kong et al., 2007).

"The 'MGH Acupuncture Sensation Scale' (MASS) scale includes 13 descriptors: soreness, aching, deep pressure, heaviness, fullness/distension, tingling, numbness, sharp pain, dull pain, warmth, cold, throbbing, and one supplementary rows at the end for subjects to describe perceptions in their own words" (Jian Kong et al., 2007). Figure 2.1.

soreness	0	1	2	3	4	5	6	7	8 I strong	9	10
auteneaa	none		mild	÷.		moderat	e		strong	, r	Inbearab
	0	1	2	3	4	5	6	7	8	9	10
aching	none		mild		_	moderat	e		8 strong	-	unbearab
	0	1	2	3	4	5	6	7	8	9	10
deep pressure	none	i	mild	ī	1	moderat	e	i	8 strong	ľ.	Inbearab
	0	1	2	3	4	5	6	7	8	9	10
heaviness	none	-	mild		-	moderat	e		8 strong		Inbearab
	0	1	2	3	4	5	6	7	8 strong	9	10
fullness/distention	none	_	mild	_		moderat	e		strong		Inbearab
tingling	0	1	2	3	4	5	6	7	8 strong	9	10
ungling	none		mild			moderat	e		strong	ľ	Inbearab
numbness	0 L	1	2	3	4	5	6	7	8 strong	9	10
numpness	none		mild	_		moderat	e		strong	ľ	unbearab
sharp pain	0 L	1	2 mild	3	4	5 I moderat	6	7	8 strong	9	10
snarp pain	none		mild			moderat	e		strong	L	unbearat
dull pain	0	1	2 mild	3	4	5	6	7	8 strong	9	10
	none		mild			moderat	e	-1	strong	,	Inbearat
warmth	0 L	1	2	3	4	5	6	7	8 strong	9	10
	none		mild		3	moderat	e		strong	L	unbearab
cold	0	1	2	3	4	5	6	7	8 strong	9	10
	none		mild			moderat	e		strong	L	unbearab
throbbing	0	1	2	3	4	5	6	7	8 strong	9	10
	none		mild		21	moderat	e		strong		unbearab
other	0	1	2	3	4	5	6	7	8 strong	9	10
(subject defined)	none		mild			moderat	6		strong		Inbearab

Figure 2-1 "The Massachusetts General Hospital acupuncture sensation scales (MASS). The scale includes 13 descriptors: soreness, aching, deep pressure, heaviness, fullness/distension, tingling, numbness, sharp pain, dull pain, warmth, cold, throbbing, and a subject defined" (Jian Kong et al., 2007).

Overall, in the research of modern acupuncture, researchers pay more attention to how to transfer the technology of acupuncture scientifically, and it will help the next generation to learn better. For example, The electrodermal screening test (EDST) and electrodermal screening device (EDSD) used in acupuncture in 1996, it was a connection between the quantum mechanics and acupuncture treatment (Tsuei, J., 1996).

2.2.2 Learning Tools in Acupuncture

2.2.2.1 Traditional Learning Tools

From the 3rd Century AD onwards, with the development of acupuncture in China, acupuncture became a more and more professional discipline, because of various professional books created by acupuncturists, such as *Zhenjiu Jiayi Jing* (Kan-Wen Ma, 2000).

Firstly, a book called *Zhenjiu Jiayi Jing* (A Classic of Acupuncture and Moxibustion) compiled by Huangfu Mi (214-282) between 259 and 260 (Kan-Wen Ma, 2000). It was a professional acupuncture teaching book which illustrated the name and number of points of each Channel and their exact locations, and the properties and indications of each acupoint and the methods of needling detailedly. Huangfu Mi created the book through the method which combines the theoretical knowledge and clinical experiences (Kan-Wen Ma, 2000).

Secondly, in 1023, a court physician called Wang Weiyi (approx 987-1067) wrote a book to describe the theory of acupuncture points and Channels under the order of the Song government. At the same time, he built two life-size bronze acupuncture figures cast and inscribed with Channels and points on them to aid people in understanding the knowledge of acupuncture (Kan-Wen Ma, 2000). The title of the book was Tong *Ren Shu Xue Zhen Jiu Tu Jing* (Illustrated Classic of Acupuncture and Moxibustion Points as Demonstrated on the Bronze Figure), it discussed the 359 acupuncture points detailedly, and the depth of each acupoint (Kan-Wen Ma, 2000). Following the book, the professional acupuncturists could find the detailed introduction and function of each acupuncture point. This book and the two life-size bronze acupuncture figures cast were the most important learning tools in the traditional teaching of acupuncture.

2.2.2.2 Modern Learning Methods

As far as the learning method is concerned, in the modern teaching methods of acupuncture, acupuncture is closely related to anatomy. "Treatment with acupuncture

consists of the insertion through the skin of solid needles from 15 to 50 mm in length. The depth of insertion varies from a few millimeters to several centimeters. The tip of the needle often lies in a muscle, but many recognized acupuncture points overlie other structures, including the nerves and pleura;" therefore, acupuncturists need an operating knowledge of anatomy and understanding the relationship between anatomy and acupuncture to avoid causing direct harm to the body (Elmar T. Peuker et al., 1999).

Concerning the learning system in acupuncture, the practical teaching of acupuncture followed the method of combining the theory learning and the practical training. According to the technique points of actual education, the teachers established training methods and evaluation form and listed full aspects of self-evaluation and mutual evaluation (Han, H. et al., 2016). This is a modern learning method of acupuncture to connect the theory learning and practice with the assessment.

2.3 Virtual Reality

In this part, the definition and features of VR will be described, and it also will discuss the application of VR in medical education.

2.3.1 Description of Virtual Reality

2.3.1.1 Definition of Virtual Reality

Virtual Reality is a form of technology which is coined by Jaron Lanier in 1989 to put all virtual projects under one name (Krueger, 1991). Virtual Reality is usually a combination of hardware, including computers, headsets, and motion sensors (Steuer, J., 1992). Generally speaking, in the Virtual Reality system, the user wears the stereoscopic display to connect the virtual environment and uses the sensor to carry on the interactive information transmission with the virtual environment. Image output is carried out in a stereoscopic display (Steuer, J., 1992).

With the deepening of research, people have a deep understanding of Virtual Reality(VR) from the technical level to the perceptual level. Virtual Reality has become an immersive experience, highlighting the user's individual feeling in the virtual environment. Therefore, Virtual Reality is combined with the ability of perception and interaction.

2.3.1.2 Features of Virtual Reality

About the features of Virtual Reality(VR), firstly, Virtual Reality uses computer graphics to simulate a real world in which the users can input different instructions to achieve the real-time interactivity (Grigore C. Burdea, 2003). Secondly, simulation is another vital feature of VR. VR focuses on not only seeing the images on the screen but also feeling them in the virtual environment (Burdea, 1996). Virtual Reality established the multilevel computer interface and used all of the sensory channels of the body to make a concurrent virtual environment (Codella et al., 1993). Thus, the feeling of immersion and simulation are also the features of Virtual Reality.

2.3.2 Virtual Reality in Medical Education

According to Millar's research, Virtual Reality(VR) is an excellent learning tool in the teaching and training field. Because the 3D simulator environment could help the users understanding the knowledge well and making the interactive operation. People can enter a VR world which has been established or build their VR world. The presentation and interaction of a VR world are consistent with actions in our physical world (Byrne, 1992).

VR has the incredible potential in the medical education, nowadays, more and more simulator training are established by the virtual environment to improve the skill ability of the medical students (Hoffman, H., 1995). The VR-based environment can provide a 3D visual environment for the users understanding the structure of the human tissues, and also encourage the users to interact with the virtual environment (Hoffman, H., 1995). For example, research in anesthetic simulation in 2006, these simulators combined a manikin with specific computer controls that could be manipulated in the virtual environment to provide various physiological outputs (Bradley P., 2006). It was an accurate and repeated operation training equipment to help students do the anesthetic simulation. Also, in 2009, researchers developed the 'Karlsruhe Endoscopic Surgery Trainer,' which is a VR technology-based training system for laparoscopic surgery (Kuhn, Ch. et al., 2009). The VR training system taught surgeons new procedures and determined their ability level before they operated on patients.

2.4 Haptic Technology

In this part, the description of the haptic device and the application of haptic technology in medical education will be illustrated.

2.4.1 Haptic Device

"The word haptics, believed to be derived from the Greek word haptesthai, means related to the sense of touch. In the psychology and neuroscience literature, haptics is the study of human touch sensing, specifically via kinesthetic (force/position) and cutaneous (tactile) receptors, associated with perception and manipulation. In the robotics and virtual reality literature, haptics is broadly defined as real and simulated touch interactions between robots, humans, and practical, remote, or simulated environments, in various combinations" (Handbook of Robotics, Siciliano, 2016).

The user can experience tactile sensation in the environment and feel the feedback of tactile force interactively. Besides, the user also can feel the tactile performance in the operating environment (Handbook of Robotics, Siciliano, 2016).

Figure 2-2 shows the haptic loop. It is composed of a haptic device, a controlled computer environment, and an interactive platform.

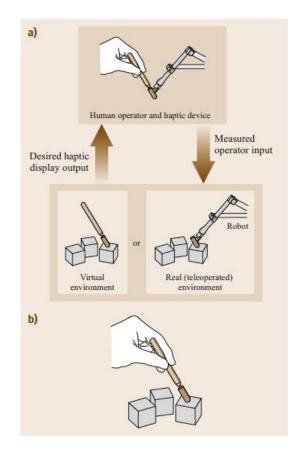


Figure 2-2 The haptic loop (Handbook of Robotics, Siciliano, 2016).

Firstly, the tactile device tests the operator's input force through the haptic device's force feedback which is produced by the user's input. Second, the input information is connected to the virtual environment. In the virtual environment, the input force information has an impact on the overall virtual environment. At the same time, the tactile device interacts with the real environment, and the tactile force transmits the tactile information to the user. Finally, the user feels the tactile force feedback on the tactile device. This complete haptic loop repeats itself in the haptic system (Handbook of Robotics, Siciliano, 2016).

2.4.2 Haptic Technology in Medical Education

The haptic technology can be used for people to train some skills to combine with the virtual display, which need the hand-eye coordination, such as the surgical training (Maharashtra, 2015). The haptic device has a broad application within virtual medical training applications, and mainly, it can be used to help doctors to plan an operation and train skills (Coles, T.R. et al., 2010). For example, in 2012, the researchers established an intravenous simulator incorporating virtual reality and haptics device technologies (Jung Eun-Yang et al., 2012). It was a haptic training aid used by medical and nursing colleges with IV arms designed for IV injection PE. Furthermore, in the example, the researchers also evaluated the simulator training. The virtual and haptic simulator training method could help the students learn injection skills well and complete injections quickly (Jung Eun-Yang et al., 2012).

Also, nowadays, the patient safety is becoming more and more concerned, in particular, considering the medical process and technology (Coles, T.R. et al., 2010). Safe practice of operation becomes more and more critical, and the operator needs to respond correctly to both visual and haptic actions. Therefore, medical simulator becomes a more accepted tool to train the process of operation. For example, in 2001, the researcher made an exploration of graphical and haptic simulation of the laparoscopic common bile duct (Basdogan, B., 2001). The researcher simulated a surgical procedure that involved inserting a catheter into the cystic duct using a pair of laparoscopic forceps. In this research, the user could be trained to grasp and add a flexible moving catheter into the deformable cystic duct in a virtual environment. In the process of training, the user could see the related images on the computer screen and feel the haptic feedback.

2.5 Virtual Simulation and Integrated in Acupuncture

Simulation-based learning is an effective learning method for the learning and training of acupuncture. In the traditional teaching method of acupuncture, in 1027, Wang Weiyi established two bronze real-size statutes for teaching acupuncture and surface anatomy. It was a useful attempt at simulated learning (Proceedings of the Saudi Health Simulation Conference 2018, 2018). The following lists three examples about the research combining the virtual simulation and integrated haptics in acupuncture.

Firstly, in 2006, using the virtual reality technology, researchers developed an intelligent virtual environment for the study and training of acupuncture in China. This was the first step in improving the overall virtual environment for the study of Chinese medicine. Students could learn and practice acupuncture in an advanced 3D interactive virtual environment that supported by a force feedback interface for acupuncture. Therefore, students could not only "see" but also "feel" virtual patients (Heng et al., 2006). Figure 2-3 Needle puncture on the acupoint Sanyinjiao (Heng et al., 2006). Figure 2-4 User interface and operation situation of the research (Heng et al., 2006).

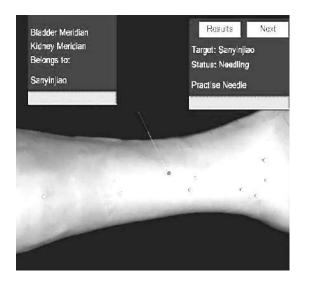


Figure 2-3 Needle puncture on the acupoint Sanyinjiao (Heng et al., 2006).

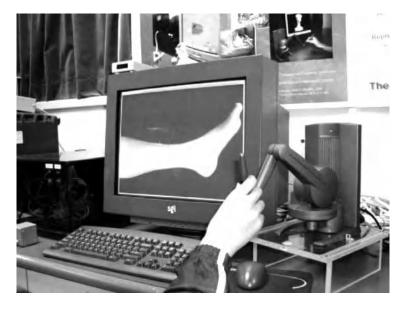


Figure 2-4 User interface and operation situation of the research (Heng et al., 2006).

In the research, it was an attempt combining the acupuncture with the simulator haptic technologies. It pointed out the data analysis of force in the acupuncture and thought the system had a reasonable force feedback result (Heng et al., 2006).

Secondly, in 2014, researchers made a study to compare and measure the force of penetrating the six acupuncture points and establishing a platform to simulate the needling force. Also, the doctors of Korean medicine made an evaluation and feedback about the accuracy of the needling force (Lee In-Seon et al., 2014). It was a haptic simulation for acupuncture needle manipulation, which pointed out the biomechanical forces of six human acupoints. Figure 2-5 shows the changing of the power in haptic simulation for acupuncture.

HAPTIC SIMULATION FOR ACUPUNCTURE

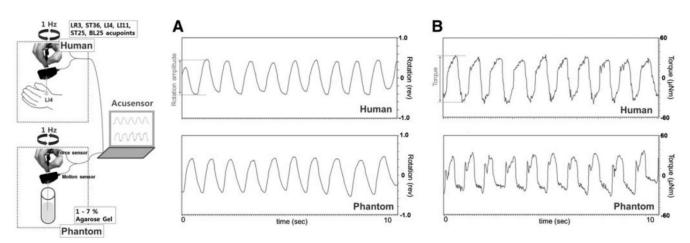


Figure 2-5 The changing of the force in haptic simulation for acupuncture (Lee In-Seon et al., 2014).

Thirdly, in 2016, the three-dimensional structure of acupoint anatomy was integrated into the teaching of acupuncture manipulation. Combined with the implementation and application of the acupuncture and moxibustion in digital virtual human (Jiang et al., 2016). Figure 2-6. In this research, on the one hand, based on VOXEL-MAN (Karl Heinz Hohne,1984) Figure 2-7 virtual human development platform, researchers finished the three-dimensional browser redevelopment of the science of acupuncture and moxibustion of Shu acupoint, which provided visual perception for people. On the other hand, based on modern biomechanics theory, researchers established models for graphics and image processing technology and force feedback technology. The

657

stress process of the structure of each layer in the acupuncture point area was given to people in the sense of touch by the manner of virtual reality and force feedback (Jiang et al., 2016).

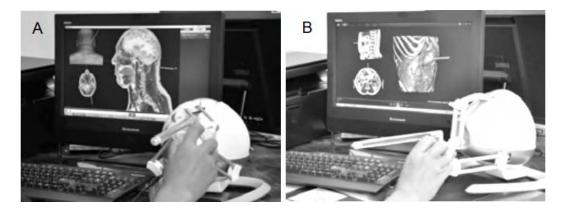


Figure 2-6 The simulator needling training situation (Jiang et al., 2016)



Figure 2 -7 The Voxel-Man System (Voxel-Man, 1984).

Figure 2-7 shows the Voxel-Man System, which was established by 3D visualization of tomographic images from CT. The reference address is https://www.voxel-man.com/about/.

2.6 Conclusion

First of all, the discussed above refers to two main parts, the simulator and haptic technologies in medical education and the application of simulation and haptics in acupuncture. As I mentioned before, establishing the simulated and haptic training system is an effective and modern method to teach and exercise the operation of medical knowledge. It not only can make the learners "see" the medical rationale but also help them "touch" the practical exercising.

The VR anatomical learning and haptic acupuncture training are combined in the project. The application focuses on two parts, firstly, deliver the knowledge of acupuncture and anatomy to the next generation clearly and visually. Secondly, making an accurate acupuncture feedback platform to train the acupuncture. Therefore, it is essential to get the tactile feedback correct, or it will provide the incorrect training for the learners.

3 Materials and Methods

3.1 Materials

In this part, the physical contents of the project will be illustrated, and these materials are divided into three sections, the image and model of medical information, the hardware and the software.

3.1.1 Medical Image Information and models

3.1.1.1 Image Information

The image information used in the project consists of open resources which could be found in books and papers. The following is a table with the information that has been used to organize the anatomical structures within the project.

Image Information	Description	Reference
Human anatomical image:	Understanding the female	These images are from
Thorax	thoracic structure. Figure:	Netter's clinical anatomy.
	3-1-1	Images are published in a
Human anatomical image:	Understanding the	book called Atlas of
Forearm	structure of the forearm,	Human Anatomy, authored
	especially the muscles	by Netter
	forming. Figure: 3-1-2	(Netter, F., 2011).

Table 3-1 Illustrating the information of image and reference.

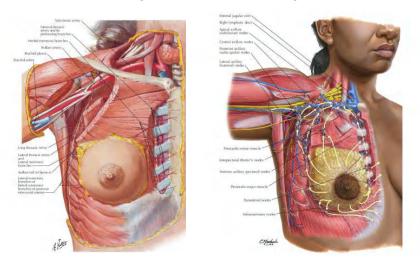


Figure 3-1-1 Human anatomical image: Thorax (Atlas of Human Anatomy, 2011).

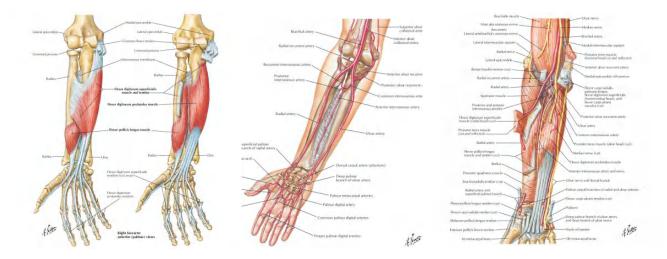


Figure 3-1-2 Human anatomical image: Forearm (Atlas of Human Anatomy, 2011).

3.1.1.2 Models

A part of models used in the project consists of open resources which were bought to online ANATOMY MODELS STORE. The following is a table with the information that has been used to organize models within the application.

Model Information	Description	Reference
Human Female Anatomy	Models of correct structure	The model could be
Complete 3D Model Pack	and proportion in body	bought to online
	systems. Figure: 3-2-1	ANATOMY MODELS
		STORE, and the following
		is the online address.
		https://www.plasticboy.co.u
		k/store/MAYA-Rigged-Hum
		an-Female-Anatomy-Com
		<u>plete-V07.html</u>

Table 3-2 Illustrating the information of models and reference.

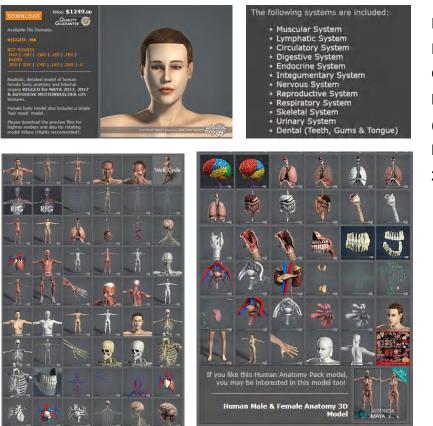


Figure3-2-1Human Female Anatomy Complete 3D Model Pack (ANATOMY MODELS STORE, 2011). The Glasgow School of Art supplies the hardware of the project. Hardware requirements must be met the running of the application and the development of the plan. Table 3-3 lists the specific requirements of the computer to run the virtual environment by HTC Vive and Phantom Omni. Furthermore, the detailed equipment description will be mentioned in Table 3-4 and Table 3-5.

3.1.2.1 Computer Requirement

In the following two tables, the first table is the minimum requirement for the computer to run the application. And the second one is the configuration of the computer to show the demo in GSA.

Recommend Computer Spaces	Description	Reference
Graphics	NVIDIA® GeForce® GTX 1060 or AMD Radeon™ RX 480, equivalent or better	The configuration of computer is mentioned on the website of HTC Vive
Processor	Intel® Core™ i5-4590 or AMD FX™ 8350, equivalent or better	(HTC, 2015). The following is the address
Memory	4 GB RAM or more	of the website.
Video out	HDMI 1.4, DisplayPort 1.2 or newer	https://www.vive.com/uk
USB ports	1x USB 2.0 or better port	
Operating system	Windows® 7 SP1, Windows® 8.1 or later, Windows® 10	

Table 3-3 listing the specific requirements of the computer in the project.

Table 3-3-1 The minimum requirement for the computer to run application (HTC, 2015).

Computer Spaces	Description	Reference	
Graphics	NVIDIA GeForce GTX 1080	The configuration of	
Processor	Intel® Core™ i7-7820HK CPU @	computer is mentioned on	
	2.9GHz	the website of MSI (MSI,	
Memory	16.0GB	2017).	
OS	Windows 10	The following is the address	
		of the website.	
		https://uk.msi.com/	

Table 3-3-2 The configuration of the computer to show the demo in GSA (MSI, 2017).

3.1.2.2 HTC Vive Detailed Description

HTC Vive is the critical equipment to achieve the virtual environment. In this part, the detailed information of HTC Vive will be illustrated, and it contains the structure, the data, the description and the reference to each piece of the equipment.

Structure	Information	Description	Reference
Headset	- Adjustable straps and	The virtual	The detailed
	interchangeable inserts	environment could	description of each
	- Front-facing camera	be shown by the	part of the
	- Eye relief adjustments	headset. Figure	equipment is open
	- Fits most glasses (HTC	3-4-1.	resource on HTC
	Vive, 2015)		Vive website (HTC
Controller	- Designed exclusively for	People could track	Vive, 2015).
	VR	or move objects in	https://www.vive.co
	- Intuitive controls and	the virtual	<u>m/uk</u>
	gestures	environment by the	
	- Realistic HD haptic	controller; it means	
	feedback (HTC Vive, 2015)	the controller is the	
		tool to achieve	
		interaction between	
		the virtual	
		environment and	

		learners. Figure	
		3-4-2.	
Base	- 360-degree play area	It builds the 3D	
Stations	tracking coverage	space to run the	
	- Wireless syncing	application.	
	- Fits standard threaded	The minimum	
	mounting points (HTC Vive,	space is 1.5m * 2m.	
	2015)	Figure 3-4-3.	

Table 3-4 the detailed description of HTC Vive (HTC Vive, 2015).



Figure 3-4-1 Headset (HTC Vive, 2015)



Figure 3-4-2 Controller (HTC Vive, 2015)





Figure 3-4-3 Base Stations (HTC Vive, 2015)

Figure 3-4-4 HTC Vive Playing Space (HTC Vive, 2015)

3.1.2.3 Phantom Omni Detailed Description

The Phantom Omni is a commercial, portable haptic device with Six Degrees of Freedom (DoF) developed by Sensable Technologies. It is widely used in various applications, including simulation, training, machine interface design, mapping and dozens of other applications (SensAble, 1994).

Table 3-5 lists detailed information of the haptic. Table 3-6 illustrates the Six Degrees of Freedom (6DoF) in the haptics.

Model	The Phantom Omni Device	Reference
Force feedback		The device evolved from
	~6.4 W x 4.8 H x 2.8 D in	
workspace	> 160 W x 120 H x 70 D mm	research done by Thomas
Footprint Physical	6 5/8 W x 8 D in	Massie and Dr. Kenneth
area the base of	~168 W x 203 D mm	Salisbury at MIT
device occupies on		(SensAble, 1994). The
the desk		following website address
Weight (device only)	3 lb 15 oz	could find the more
Range of motion	Hand movement pivoting at the	information and resources.
	wrist	www.sensable.com/suppor
Nominal position	> 450 dpi	<u>t-overview.htm</u>
resolution	~ 0.055 mm	
Backdrive friction	<1 oz(0.26 N)	
Maximum exertable	0.75 lbf. (3.3 N)	
force at nominal		
(orthogonal arms)		
position		
Continuous	> 0.2 lbf. (0.88 N)	
exertable force (24		
hrs.)		
Stiffness	X axis > 7.3 lb/in (1.26 N/mm)	
	Y axis > 13.4 lb/in (2.31 N/mm)	
	Z axis > 5.9 lb/in (1.02 N/mm)	

3.1.2.3.1 The information of Phantom Omni

Inertia (apparent	~0.101 lbm. (45 g)
mass at tip)	
Force feedback	Х,У,Ζ
Position sensing	x, y, z (digital encoders)
[Stylus gimbal]	[Pitch, roll, yaw (± 5% linearity
	potentiometers)]
Interface	IEEE-1394 FireWire® port:
	6-pin to 6-pin*
Supported platforms	Intel or AMD-based PCs
OpenHaptics® SDK	Yes
compatibility	

Table 3-5 The detailed description of Phantom Omni (SensAble, 1994).https://www.virtalis.com/wp-content/uploads/phantom_omni_spec.pdf



Figure 3-5-1 The modeling of Phantom Omni (SensAble, 1994).

3.1.2.3.2 Six Degrees of Freedom (6DoF) in Phantom Omni

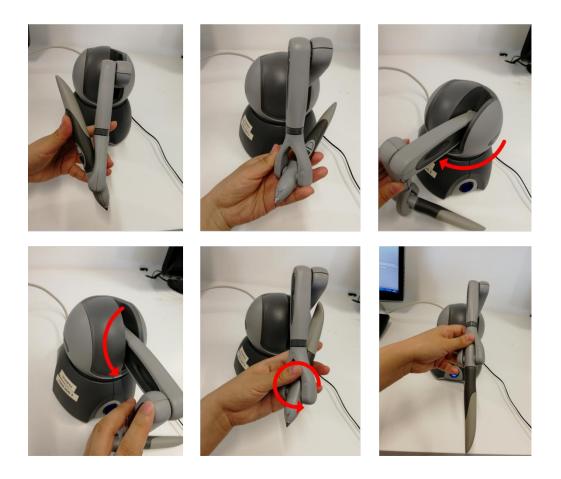


Table 3-6 The Six Degrees of Freedom (6DoF) in the haptic device.

3.1.3 Software

Table 3-7 is a list of software that has been used to establish the application. The list includes the software to build the programming in the project and the 3D model software to create the virtual environment. Besides, image and video software are used to construct the interacted interface and the introduction video.

Software	Description	Reference
3DS Max	Cutting the 3D modeling and	https://www.autodesk.co.uk/
	changing the texture.	products/3ds-max
Maya 🚺	Cutting the 3D modeling and	https://www.autodesk.co.uk/
	changing the texture.	products/maya
Adobe Ps	User interface	https://www.adobe.com
Photoshop		
Adobe Ai	User interface; Type design;	https://www.adobe.com
Illustrator	Logo design; Storyboard and so	
	on.	
Flash	Designing the introduction video.	https://www.adobe.com
Adobe Ae	Designing the introduction video.	https://www.adobe.com
After Effects		
Goldwave G	Editing the audio.	https://www.goldwave.com
Unity 🔂 unity	Organizing the virtual	https://unity3d.com/cn
3D	environment; Programming the	
	functions with C#; Combining	
	the Steam VR and Haptic Plugin.	
MonoDevelo	Scripting with C#, in-build into	https://www.monodevelop.c
(in-build to	Unity 3D.	<u>om</u>
Unity 3D)		
SteamVR Plugin	Steam VR Plugin is fixed into the	https://assetstore.unity.com/
Steam VR	Unity 3D to build the simulated	packages/templates/system
	environment.	<u>s/steamvr-plugin</u>
VRTK - VR Toolkit	VR Toolkit Plugin is used to	https://assetstore.unity.com/
Plugin	establish the button interaction	packages/tools/vrtk-virtual-r
	in the virtual environment.	eality-toolkit-vr-toolkit-64131
OpenHaptics	OpenHaptics Plugin is fixed into	https://assetstore.unity.com/
Plugin	the Unity 3D to establish the	packages/essentials/tutorial-
Unity 5 Haptic Plugin for	integrated haptic interaction.	projects/unity-5-haptic-plugi
Geomagic OpenHaptics 3.3		n-for-geomagic-openhaptics

Table 3-7 List of software used for the application, including a description of their use.

3.2 Methods

The following flowchart shows an overview of the design process for the application.

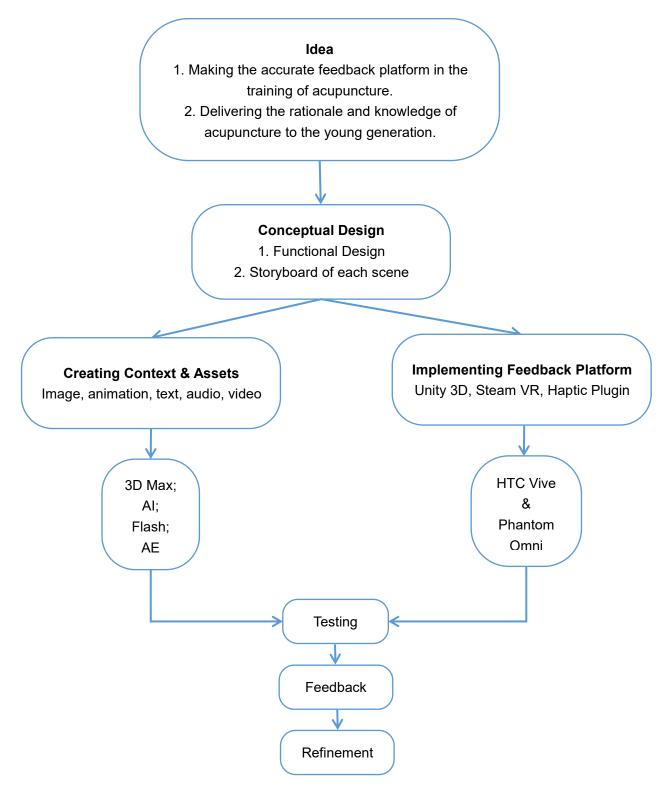


Table 3-8 Flowchart of the design process for the application.

3.2.1 Requirements

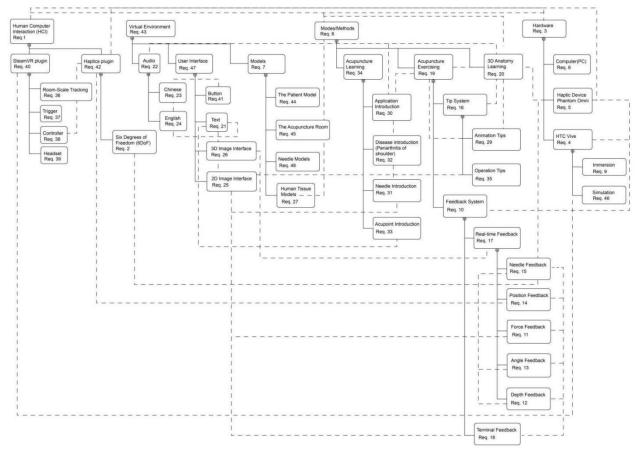
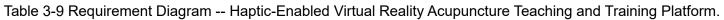


Table 3-9 and Table 3-9-1 show an overview of the functional requirements of the application.



Requiremen t Number	Requiremen t	Description	Rationale	Paren t	Childre n	Related Req.	Verification	Order
1	Name Human-Com puter Interaction(H CI)	The system must achieve the unity and harmony between the application and users.	The concept of interaction contains the communication between the hardware and software with human and the cognitive and emotional aspects of the user's experience. The interaction can be divided into the tangible and intangible two aspects (Laurel, B., Joy	-	40.42	3	In the project, the user will have a fluent interaction between the equipment and software. Also, the user will achieve a comfortable and friendly operation feeling.	Compulsory
2	Six Degrees of Freedom (6DoF)	6DoF must be provided for users in the system.	Mountford S., 1990). The rigid body is free to change position as forwarding/backward (surge), up/down (heave), left/right (sway) translation in three perpendicular axes, combined with changes in orientation through rotation about three perpendicular axes, often termed yaw (normal axis), pitch (transverse axis), and roll (longitudinal axis).(Srivastava, M.K., 2017) In the object, it has the	42	-	5	In the application, hand movement pivoting at the wrist by Phantom Omni. This includes the moving and tracking in six different directions in the 3D space.	Compulsory

			accurate tracking following the six directions. It also provides flexible methods of interaction (Req. 1) .					
3	Hardware	Suitable hardware equipment is provided to run the project.	The hardware is the fundamental condition to run the application. It contains the appropriate computer requirements (Req.6), HTC Vive (Req.4)and Phantom Omni (Req.5).	-	6.4.5	1	The user will use HTC Vive to see the virtual environment, and the Phantom Omni (Haptic device) to achieve the interaction between the virtual environment and users.	Compulsory
4	HTC Vive	The system contains the headset, controllers and base stations.	HTC Vive is a virtual reality(VR) device to establish the connection between the real world and the virtual environment (Req.43). It provides an immersive experience (Req.9).	3	9.46	40.43	The user wears HTC Vive equipment to experience the application. And the user will see the immersive world by the headset.	Compulsory
5	Phantom Omni	The system allows the user to build the interaction between the virtual environment and themselves.	Phantom Omni is a haptic feedback device. The user could experience 6DoF when using the device to penetrate the skin. Furthermore, the user will experience the different force (Req.11), angle (Req.13), position (Req14.) by the device. The	3	-	42.19	The user will get accurate feedback from it, and the Phantom Omni is the object to get the user interacts.	Compulsory

			device is the key point to achieve the user interaction (Req.1).					
6	Computer (PC)	The system is the clear condition about running the object on PC.	Computer requirements mention the minimum requirements to run the object smoothly. It contains the computer requirements with HTC Vive (Req.4) and Phantom Omni (Req.5).	3	-	-	The project can only run if the computer meets minimum configuration requirements.	Compulsory
7	Models	All models are used to establish the virtual environment.	Models are divided into three kinds. The first part is the model of the acupuncture room (Req.45), the second one is the patient model (Req.44). Thirdly, it is the colorful needle models (Req.48). Finally, it is the human tissue models (Req.27).	43	44.454 8.27	-	All models are used in the virtual environment. Therefore, the user will see them when they wear the headset.	Compulsory
8	Methods / Modes	The system has four different methods to learn and exercise acupuncture.	Firstly, the user will understand the points of acupuncture (Req.34), and learn the relationship between the acupuncture and the anatomy (Req.20). Furthermore, the user could exercise the operation of	-	34.19.2 0	3.1.43	The application will be constituted by these four methods, and the user could learn and exercise acupuncture following by the system.	Compulsory

			acupuncture (Req.19), and get real-time feedback (Req.17) and the terminal feedback (Req.18).					
9	Immersion	The application provides an immersive environment to make the user experience better operation system, and immersive interaction.	Immersive experience hopes the user could feel the real world in a virtual environment (Req.43) . And the user could do the operation of acupuncture and learn anatomy and acupuncture in the virtual environment.	4	-	43	The user could make interaction within the virtual environment by the equipment.	Compulsory
10	Feedback system	The feedback system could be divided into two types. The first one is real-time feedback and the second one is terminal feedback.	The real-time feedback (Req.17) means the user could see the operation of acupuncture directly and get the 3D image feedback in the process of exercising. The user records a terminal image about every part of one acupuncture point after the operation. Finally, the user could get terminal feedback (Req.18) and evaluation by the professional acupuncturist after the total treatment operation.	19	17.18	5	The user could get the real-time and terminal feedback in the process of operation and after the whole operation. At the end of the application, the user also will get an evaluation and level of the total exercising.	Compulsory

11	Force	The system	The force feedback of	17.18	-	25	The user will get	Compulsory
	feedback	provides the feedback about the force of each	operation could be shown by a 2D chart interface (Req.25).				feedback in the process of operation.	
		acupoint.	(1.64.20).					
12	Depth feedback	The system provides the feedback about the depth of acupoint.	The depth feedback of operation could be shown by a 3D internal structure interface (Req.26) .	17.18	-	26	The user will get feedback in the process of operation.	Compulsory
13	Angle feedback	The system provides the feedback about the angle of penetration.	The angle feedback of operation could be shown by a 3D image interface (Req.26).	17.18	-	26	The user will get feedback in the process of operation.	Compulsory
14	Position feedback	The system provides the feedback about the position of acupoint.	The position feedback of operation could be shown by a 3D image interface (Req.26).	17.18	-	26	The user will get feedback in the process of operation.	Compulsory
15	Needle feedback	The system provides the function of choosing needle in the application.	For the user to learn the knowledge of different needles.	17.18	-	25	The needle feedback makes the user learn the accurate information of the needle and choose the correct one to do the operation.	Compulsory
16	Tip system	The tip system provides a reminder to the	The audio reminder (Req.22) could be provided in the whole application. And an	19	29.35	22	The user could use the application smoothly with these tips. And the user	Good to have

		user about the information of the correct acupoint in the application.	animation tip (Req.29) about the specific acupoint should be provided before the operation.				also could get a better preparation before the acupuncture exercising.	Compulsory
17	Real-time feedback	The real-time feedback system has five parts, the choice of the needle, the position, depth, angle and force feedback of each acupoint.	The real-time feedback has six parts, needle feedback (Req.15), position feedback (Req.14), force feedback (Req.11), angle feedback (Req.13) and depth feedback (Req.12).	10	15.14.11 13.12	5.42	The user will get real-time feedback in the process of operation.	Compulsory
18	Terminal feedback	The terminal feedback system is contained by two parts.	The terminal feedback has two parts, the acupoint terminal feedback, and the operation terminal feedback.	10	-	15.14.1 1. 13.12	The user will get terminal feedback in the process of operation.	Compulsory
19	Acupuncture exercising	The system is the main function of the application.	The aim of acupuncture exercising is remitting disease, learning the operation of acupuncture, establishing the needling feedback platform (Req.16) .	8	16.10	1.3.43	The user will exercise the operation of acupuncture by haptic device.	Compulsory
20	3D anatomy learning	The aim of the system is to learn the knowledge of anatomy by 3D images.	The 3D anatomy learning could be divided into two types, the first is acupoint anatomy(Req.29), and the second is human tissue anatomy(Req.35).	8	-	16.47.2 2	The user could learn the 3D anatomy knowledge directly and accurately in the process of exercising.	Compulsory Good to have

21	Text	The text is a	The system will help the user	47	-	23.24.3	the system will help the	Compulsory
		method of	to operate the application,			5	user to operate the	
		information	and it has two languages,				application friendly.	
		expression in the	Chinese (Req.23) and					
		application.	English (Req.24) .					
22	Audio	Audio is a method	The system will help the user	43	23.24	20.34	the system will help the	Compulsory
		of information	to operate the application,				user to operate the	
		expression in the	and it has two languages,				application friendly.	
		application.	Chinese (Req.23) and					
			English (Req.24) .					
23	Chinese	Chinese is one of	The system could have two	22	-	21	The user could get the	Optional
		the optional	parts, the first is text (Req.21)				Chinese information in	
		language systems	and the second is audio				the process of	
		in the application.	(Req.22).				application.	
24	English	English is one of	The system could have two	22	-	21	The user could get the	Optional
		the optional	parts, the first is text (Req.21)				English information in the	
		language systems	and the second is audio				process of application.	
		in the application.	(Req.22).					
25	2D image	The 2D image	The 2D image interface	47	-	47.34.2	The result of the	Compulsory
	interface	interface will be	provides the correct position			0	operation of the user will	
		shown to express	of each acupoint.				be shown on the 2D	
		the terminal result					image interface.	
		of each acupoint.						
26	3D image	The 3D image	The 3D image interface	47	-	47.34.2	The process of operation	Compulsory
	interface	interface will be	shows the real-time feedback			0	will be shown on the 3D	
		shown to express	of operation.				image interface.	
		the real-time						
		feedback.						
27	Human	Models	It will help the user to	7	-	34.19.2	The user will see the	Compulsory

	tissue models		understand the rationale and knowledge of acupuncture and anatomy.			0	model in the process of penetration.	
28	Tip system	The tip system could be divided into two types.	The tip system is divided into two types, the animation tip (Req.29) and the operation tip (Req.35).	19	29.35	20.34	The user could use the application smoothly with these tips.	Compulsory
29	Animation tips	The animation tip could help the user to do the training of acupuncture.	The acupoint tip appears at the beginning of the operation. It will help the user to know which acupoint need to penetrate. The accurate operation demo will help the user to learn the correct operation.	16	-	34.20	The user will get useful information from these tips.	Good to have
30	Application introduction	The system will help the user know the knowledge points in the application.	It contains the needle introduction (Req.25), the disease introduction, the acupoint introduction (Req29.), the acupuncture introduction and the anatomy introduction (Req.20).	34	-	22.29	The user will know the detailed information about the acupuncture and anatomy.	Compulsory
31	Needle introduction	The system is the introduction of needles.	It is a text (Req. 21) introduction about needles.	34	-	21	The user will know the detailed information about the needles.	Compulsory
32	Disease introduction (Periarthritis of the	The system is the introduction of periarthritis of the shoulder.	It is a video introduction about the disease.	34	-	22.29	The user will know the detailed information about the periarthritis of the shoulder.	Good to have

	shoulder)							
33	Acupoint introduction	The system is the introduction of acupoint.	It is audio (Req.22) and animation tip (Req.29) introduction about the acupoint.	34	-	22.29	The user will know the detailed information about the acupoint.	Good to have
34	Acupuncture learning	The system is the introduction of acupuncture.	It is audio (Req.22) and image (Req.47) introduction about the acupuncture.	8	30.32.3 1.33	22.47	The user will know the detailed information about the acupuncture.	Good to have
35	Operation tips	The operation tip could help the user exercise the needling smoothly.	The system provides tips for the user in the acupuncture exercising (Req.19) .	16	-	22.47	The user will follow these operation tips in the process of operation.	Compulsory
36	Room-scale tracking	The system is the space of the virtual environment.	It contains the HTC Vive (Req.4).	40	-	3.4	The user could move in the space.	Compulsory
37	Trigger	The system provides the method to achieve the choice function in the application.	It is a configuration of HTC Vive.	40	-	4	The user could use the trigger to choose buttons.	Compulsory
38	Controller	The system helps the developer to do the project.	The system helps the developer to make the development of functions.	40	-	42	The user will experience the controller in the process of operation.	Compulsory
39	Headset	It is a part of HTC Vive	It is a configuration of HTC Vive (Req.4) . The system is the equipment to make a	40	-	4.43	The user could see the virtual environment by the headset.	Compulsory

			connection between the real world and the virtual environment (Req43) .					
40	SteamVR plugin	The project is established based on the system.	It is the software to do the project.	1	36.37.3 8.39	4	The developer does the project by the learning of the plugin.	Compulsory
41	Button	The system provides a friendly interaction to make the user achieve more effective learning results.	The system is a part of user interface (Req.47).	47	-	16.34.2 0	The user could run the application smoothly and learn the rationale and knowledge of acupuncture by click the button.	Compulsory
42	Haptics plugin	The project is established based on the system.	It is the software to do the project.	1	2	5	The developer does the project by the learning of the plugin.	Compulsory
43	Virtual environment	The system establishes the total learning environment of the application.	it is constituted by the models(Req.7), user interface(Req.47) and audio(Req.22). It provides the running environment of the application.	-	22.47.7	1.3	The user could use the application through two devices in the virtual environment.	Compulsory
44	The patient model	The system focuses on building a realistic needling environment.	It is a part of the virtual environment (Req.43) .	7	-	34.19	It helps the user to feel realistic in the virtual environment.	Compulsory
45	The acupuncture	The system establishes a	It is a part of the virtual environment (Req.43) .	7	-	-	It helps the user to feel realistic in the virtual	Compulsory

	room	realistic needling environment.					environment.	
46	Simulation	The system points out the reality to make the user perform a true acupuncture training.	It provides real and accurate feedback of acupuncture in the application. It connects with the HTC Vive (Req.4) and Phantom Omni (Req.5) .	4	-	43	The user could feel a real acupuncture training in the virtual environment.	Compulsory
47	User interface	The system provides a comfortable interaction to the user.	It makes the application has a comfortable interaction. It is a part of HCI (Req.1) .	43	41.21.2 6.25	1	The user could run the application following the UI system.	Compulsory
48	Needle models	The systems combine with the needle feedback.	It provides a system of choosing needles and gets needle feedback (Req.15) .	7	-	15	The user could understand different types of the needle in the system.	Compulsory

Table 3-9-1 Table for the Application Requirements.

3.2.2 Design and Development

In this part, the process of design and the development of the project will be described step by step.

3.2.2.1 Storyboard of Application

After laying out the functional requirements of the application, the storyboard of the application is sketched to illustrate the design of the application.

Firstly, it is the Scene 01 - Start Menu. Figure 3-10-1.

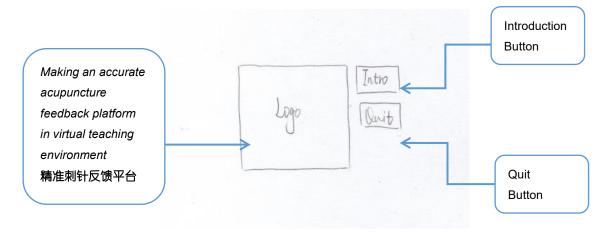


Figure 3-10-1 The sketch of the start menu.

1. The title of the application is *Making an accurate acupuncture feedback platform in virtual teaching environment*. The application has the two language system, English, and Chinese. Two languages can help more learners to understand the rationale of acupuncture.

2. The introduction button can connect with the introduction scene.

Secondly, it is the Scene 02 - Introduction. Figure 3-10-2

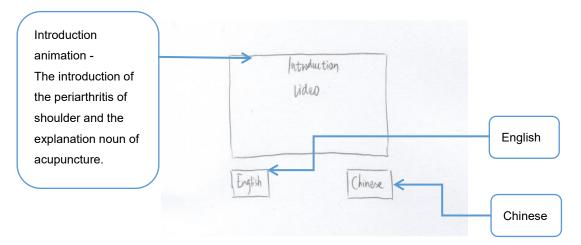
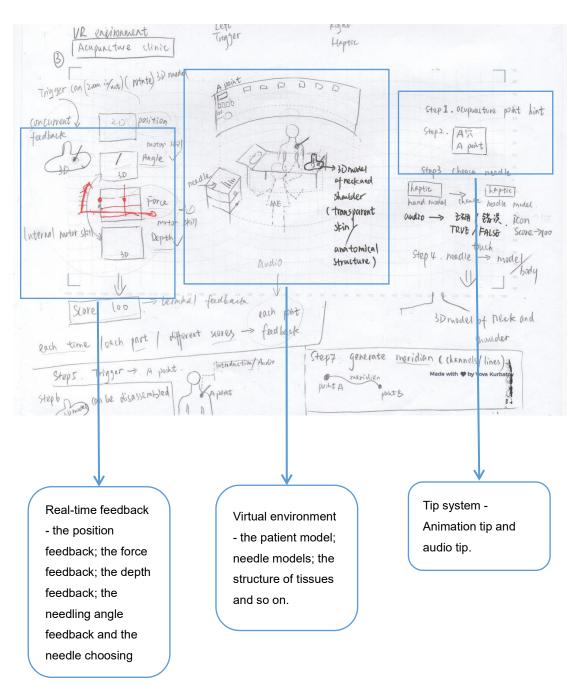


Figure 3-10-2 The sketch of the introduction interface.

 Introduction animation is designed and made by myself; it contains two parts, the introduction of the periarthritis of shoulder and the explanation noun of acupuncture.
 The user can choose a language to begin the acupuncture training.



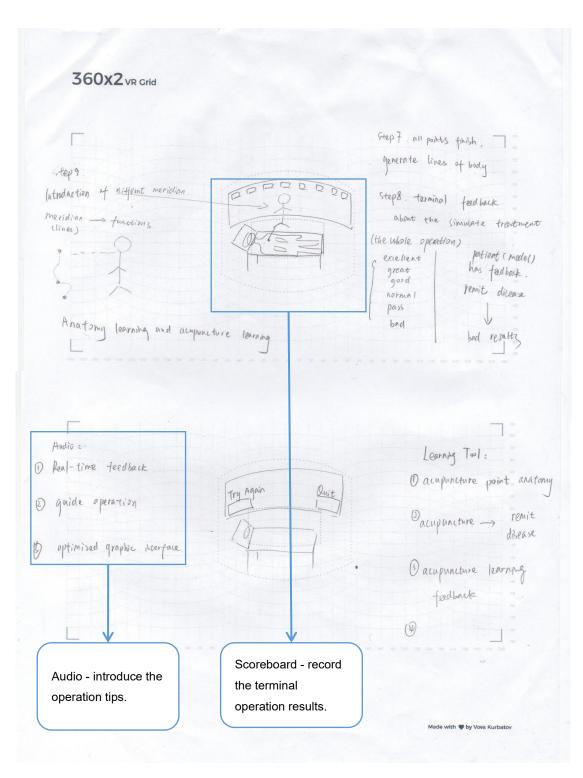
Thirdly, it is the Scene 03 - Acupuncture Training Interface. Figure 3-10-3

Figure 3-10-3 The sketch of the acupuncture training interface.

1. The virtual environment is constituted with the patient model, needle models, and the anatomical structure.

2. Real-time feedback will be shown on the Canvas in the virtual environment. The learners can get the concurrent feedback when they needle the anatomical model.

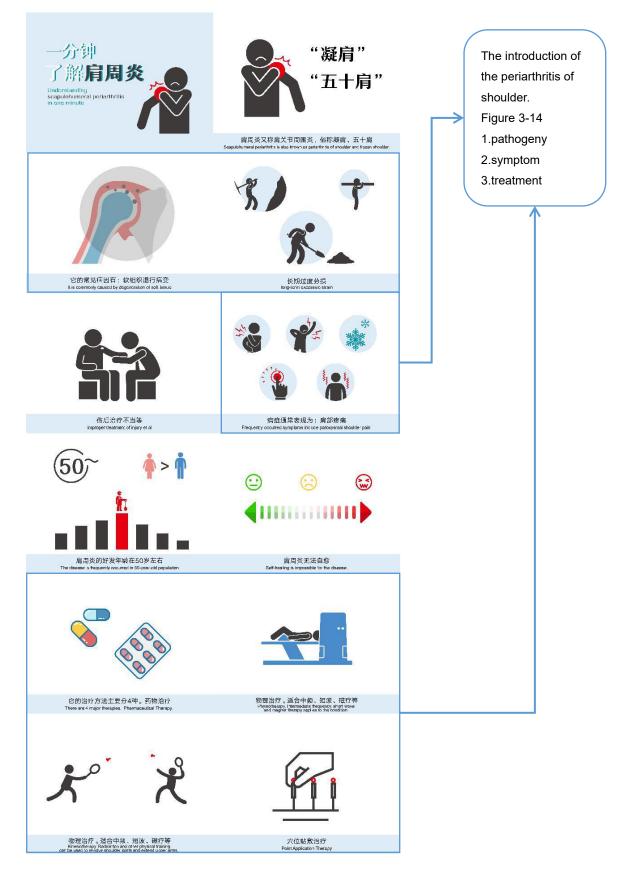
3. In the application, the user will see the animation tip before training, and these tips will help the user know the position of the acupoint.



Fourthly, it is the Scene 03 - Acupuncture Training Interface. Figure 3-10-4

Figure 3-10-4 The sketch of the acupuncture training interface.

- 1. The audio is included in the introduction of the application and the tip system.
- 2. The terminal feedback results will be recorded on the scoreboard.



3.2.2.2 Storyboard of Introduction Interface

Figure 3-10-5 The storyboard of the introduction of the periarthritis of shoulder.

Figure 3-10-5 shows the storyboard of the main pages and illustration ideas for the introduction of the periarthritis of shoulder. The storyboard is designed through the software Illustrator. In the introduction, the user can understand the pathogeny, symptom, and treatment of the disease.

Furthermore, in the introduction interface, the user also can achieve the information about the professional acupuncture term. Figure 3-10-6.

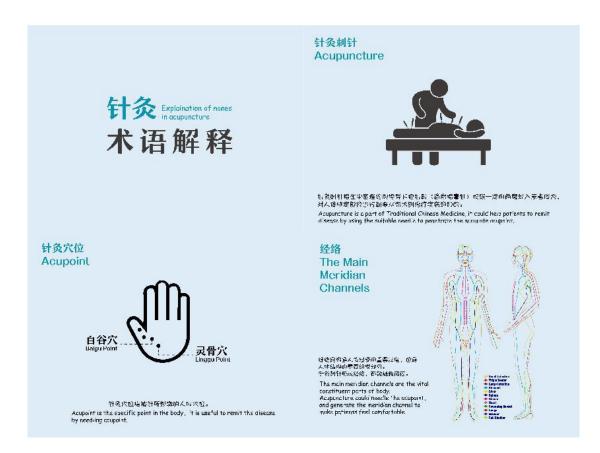


Figure 3-10-6 The storyboard of the professional acupuncture term.

Figure 3-10-6 shows the storyboard of the professional acupuncture term. In this part, the user can understand the common acupuncture term, and it is preparation before the acupuncture training.

3.2.3 Creating Context and Assets

The organizing of 3D modeling and the designing of introduction animation will be illustrated in this part.

3.2.3.1 3D Modelling

Firstly, the original 3D modeling within the project was open resources which were bought to online ANATOMY MODELS STORE. (Chapter 3.1.1.2) Figure 3-11-1

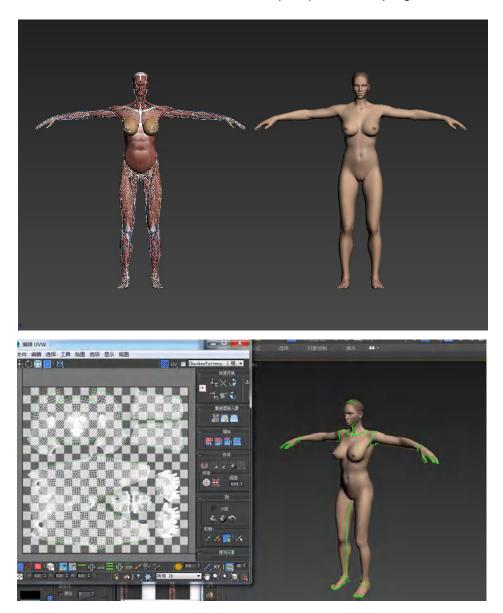


Figure 3-11-1 3D modeling - open resources in online ANATOMY MODELS STORE Human Female Anatomy Complete 3D Model Pack (ANATOMY MODELS STORE,

2011)

Secondly, change the material of the skin to make it as a translucent model through the software 3D Max. Figure 3-11-2 The original model. Figure 3-11-3 the changed model. Figure 3-11-4 the whole model with the translucent material.

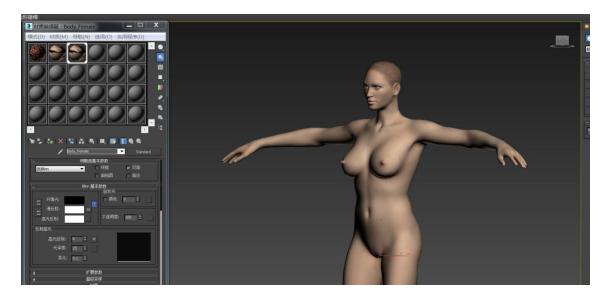


Figure 3-11-2 The original model (ANATOMY MODELS STORE, 2011)

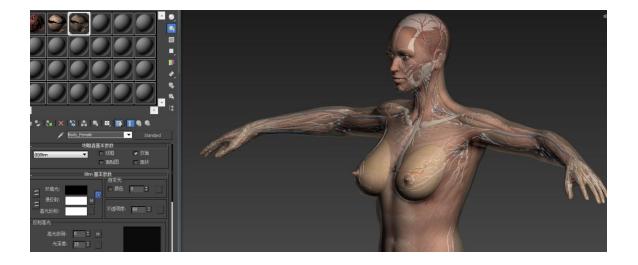


Figure 3-11-3 The changed model - using the translucent material on the skin





Figure 3-11-4 The whole model with the translucent material.

Thirdly, because the topic of the application is the treatment of the periarthritis of shoulder, I will cut the model to retain the shoulder part and the arm part by 3D Max to make the user see the anatomy clearly and understand the rationale of acupuncture. Figure 3-11-5 Cut function.

Figure 3-11-6 The cutting shoulder model. Figure 3-11-7 The cutting arm model.



Figure 3-11-5 Cut function.

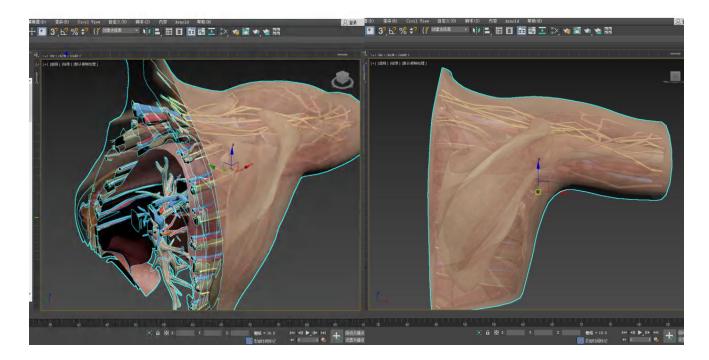


Figure 3-11-6 The cutting shoulder model.

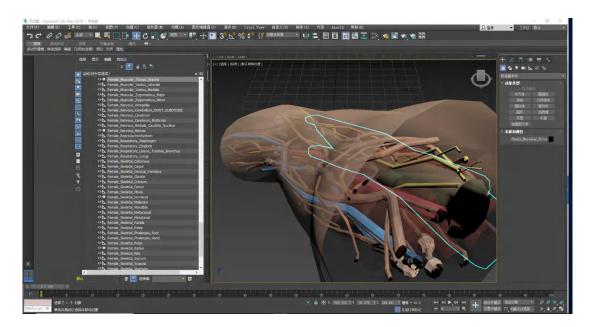




Figure 3-11-7 The cutting arm model.

3.2.3.2 Introduction Animation

Firstly, according to the storyboard (Chapter 3.2.2.2), the animation about the introduction of the periarthritis of shoulder and the acupuncture will be designed by software Flash.

Figures 3-12-1, 3-12-2.

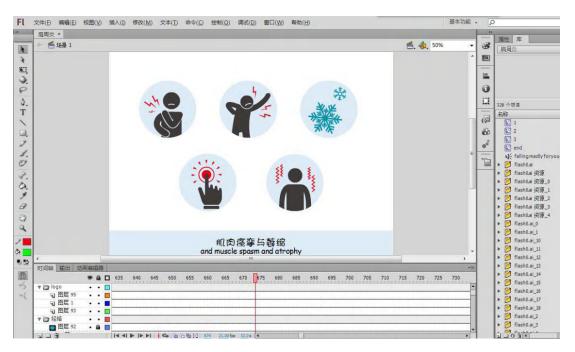


Figure 3-12-1 The process of designing the animation.

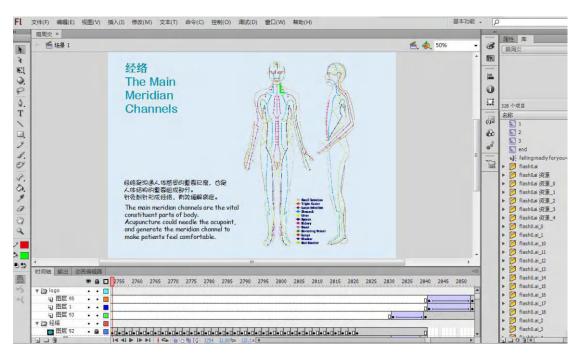


Figure 3-12-2 The process of designing the animation.

Thirdly, transform the file format of the animation and fix it in Unity 3D. Figure 3-12-3. Transform the animation into Unity step by step.

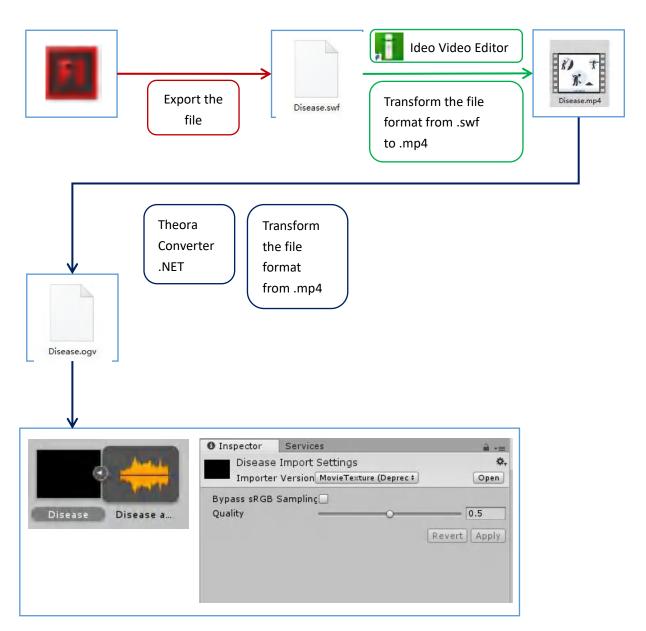


Figure 3-12-3 Transform the animation into Unity step by step.

The file format called .ogv is the only one which can run in Unity, so I need to transform the file format and import it in Unity. The ogv file is an image animation which has the separate audio.

3.2.4 Configuration for the Application

In this part, it will illustrate the configuration of the application, and some requirements when the user experiences the application.

HTC Vive's room-scale needs to be set at first. Figure 3-13-1 shows the room-scale to establish the virtual environment.



Figure 3-13-1 The room-scale to establish the virtual environment.

In the space, the user needs to prepare a desk, a chair and a suitable computer connecting with the HTC Vive and haptic device (Phantom Onmi). The user needs to sit on the chair to operate the equipment. Therefore, the virtual environment must be oriented in such a way that the user is seated. It is a vital point to experience the application. Figure 3-13-2 The correct experience situation.

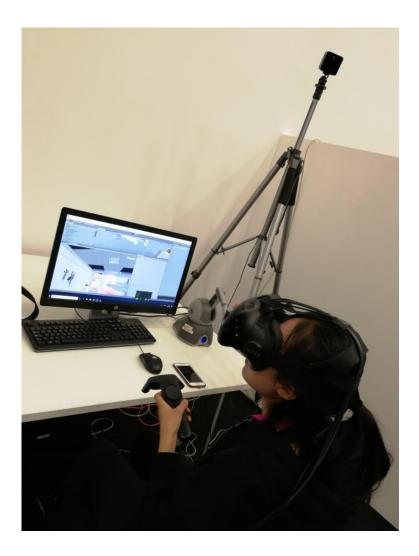


Figure 3-13-2 The correct experience situation.

3.2.5 VR Environment

In this part, it will discuss the programming connecting with the application in the environment, and the implementing of the virtual environment.

3.2.5.1 Programming of the Application in Virtual Environment

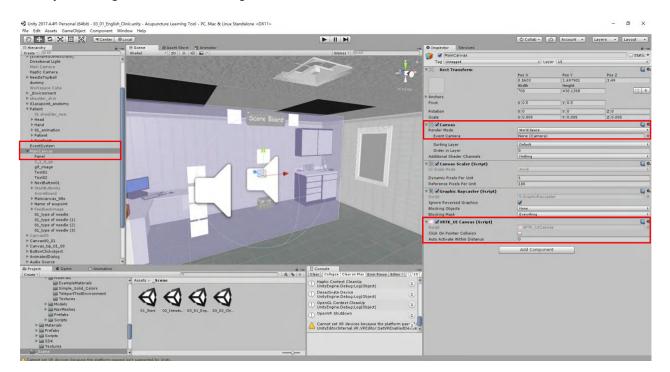
To establishing the virtual environment and interaction with HTC Vive, the headset and two controllers need to be set first. Figure 3-14-1 Setting the headset and controllers.

C+CXIIX MCenter @Lo	low Help				Account • Layers • Layout •
	# Scene @ Asset Store 1% Animator		-= O Inspector Se	vices	Account • Layers • Layout •
Create - CrAll	Shaded * 20 * 40 = *	Gizmes	s* GrAll	KManager]	Default
SteamVR VAIKESDXMenaged			Transform		
Directional Light Main Camera			Position Rotation	x 0 x 0	Y 0 2 0 Y 0 2 0
Haptic Camera NeedleTopBall	FH			X 1 fanager (Script)	Y 1 Z 1
dummy Workspace Cube			Persist On Load Scripting Define		
▶_Environment ▶ shoulder_skin			Auto Manage		Manage Now .
Diacupoint_anatomy Patient	2		V Standalone	Without SDK Classes	
EventSystem ▶ MainCanvas				IS_AVATAR (not installed)	ale.
► Canvas00 ► Canvas00_01	3		Script Aliases		
▶ Canvas_tip_01_00 ▶ ButtonClickobject ▶ AnimatedDialog		1000	Left Controller Right Controller	LeftController	
P AnimatedDialog ► Audio Source ► NeedleTopBall (1)			Setups		
Acu01_01needle feedback Sphere			Auto Manage VR S	ettings 🖉 📃	Manage Now
Sphere (1) Sphere (2)			Dophyteam (/RTK_SOKSetup) RTK_SDKSetup)	0
Sphere (3) Sphere (4)			= ChimmerseVF	(Oculus) (VRTK_SDKSetup)	0
► Acu01_ball PositionCam		1	= SteamVR (V	RTK_SDKSetup) RTK_SDKSetup)	0
		1			+ -
		F LL L		Auto Populate	
		1			
			Gray satups of new VR SDK.	ill never be loaded because either the SDK Setup isn't	valid or there is a valid Setup before it that uses any
E Project C Game O Animation		a Console		Add Component	
Create * · · · · · · · · · · · · · · · · · ·	Assets + _Scene	Haptic Context UnityEngine.Del	lear on Play Error Pause Editor 1010		
Simple_Solid_Colors	AAAA	UnityEngine.Del Desactivate De UnityEngine.Del	vice 1		
Textures	$\Theta \Theta \Theta \Theta$	UnityEngine.Del OpenGL Contex UnityEngine.Del	bug:Log(Object) t CleanUp bug: I ad(Object) 1		
► NavMeshes Prefabs	01_Start 02_Introdu. 03_01_Eng. 03_02_Chi	UnityEngine.Del	bug:Log(Object)		
+ Scripts + Materials			devices because the platform past 2		
▶ Prefebs ▶ Scripts		UnityEditorInter	mal.VR.VREditor:SetVREnabledDevide +		
E SDK					
Scene	F.				
O Inspector Services			O Inspector Services		<u>a</u>
			O Inspector Services		
👕 🖌 RightController		Static +	🝞 🗹 LeftController		🗌 Static 🔻
FightController Tag Untagged	t) Layer Default	a)	Tag Untagged	I) Layer [Default	1
👕 🖌 RightController			Tag Untagged		
Tag Lineaged Tag Lineaged Transform Position Rotation	i) Layer (Default X 0 Y 2 Z 0 X 0 Y 0 Z 0	a)	Tag Untaggad Toatsform Position Rotation	X 0 Y 2 X 0 Y 0	Z 0 Z 0
RightController Tag Unagged V. Transform Position Rotation Scale	1) Layer Default X 0 Y 2 Z 0 X 0 Y 0 Z 0 X 1 Y 1 Z 1	:)	Image: Carte Controller Tag Unnaged Tag Scale	X 0 Y 2 X 0 Y 0 X 1 Y 1	Z 0 Z 0 Z 1
Tag Lineaged Tag Lineaged Transform Position Rotation	1) Layer Default X 0 Y 2 Z 0 X 0 Y 0 Z 0 X 1 Y 1 Z 1	a)	Tag Untaggad Toatsform Position Rotation	X 0 Y 2 X 0 Y 0 X 1 Y 1	Z 0 Z 0
RightController Tog Umraged Vantaged Van	1) Layer: [Dafault X (0 Y (2 Z (0 X (0	:)	LeftController Tag Untagged LeftController Rostion Rostion Scale W RTK_Controller Events (Scrip Scope	x 0 y 2 x 0 y 0 x 1 y 1	Z 0 Z 0 Z 1
RightController Tag Untaged Position Rotation Rotation Rotation Scale WVRTE_Controller Events (Script Sorpt Action Alias Buttons Ponter Togole Button		1) (1) (0, (1) (0, (1) (0,	Cartesform	X 0 Y 2 X 0 Y 0 X 1 Y 1 VETK_ControllerEvents Teachpad Press	Z 0 Z 0 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1
RightController Tog Ustaged State A Transform Position Scale V VTL_Controller Events (Script Sorget Action Allas Buttons Pointer Toguje Button	1) Layer: [Dafault X (0 Y (2 Z (0 X (0	:)	Carticontroller Tag Lutraged Cartasform Position Rotation Scale Cartion Action Alias Buttons Pointer Toggle Button Pointer Toggle Button	× 0 Y 2 × 0 Y 0 × 1 Y 1 VETX_CantrallerEvents Teachpad Press Teachpad Press Teachpad Press Teachpad Press Teachpad Press	Z 0 Z 0 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1 Z 1
PaphtController Tog Ustaged Vertaged Ver			LaftController Tag Lutesgad Tag Lutesgad Scale V VRTK_Controller Events (Scrip Score Action Alias Buttons Pointer Togole Button Grab Toggle Button	× 0 Y 2 × 0 Y 0 x × 1 Y 1 x VETK_CantralleEvents Texchad Press Texchad Press Texchad Press Trigger Press Trigger Press Texchad Press Texchad Press	2 0 2 0 2 1 2 1 2 1 0 0 0 0
RightController Tog Untagged Autors Rotagged Autors Rotagged Konge Rotagge KVRTE_Controller Events (Script Script Action Alias Buttons Pointer Script Button Grab Toggle Button Use Toggle Button Use Toggle Button Use Toggle Button Use Toggle Button Script Script	1 Layer Default	5 0 0 0 1	Controller Tag Luftsgad Luftsgad Canasform Position Scale Cutom Alias Buttons Pointer Toggle Button Grab Toggle Button Ui Clock Button	X 0 Y 2 X 0 Y 0 X 1 Y 1 VETX_ControllerFounts Teachard Press Teachard Press Trigger Press Trigger Press	
PolphController Tog Umagged Polation Position Position Scale VortE_Controller Events (Script Script Action Allas Buttons Pointer Togle Button Pointer Set Button Use Togle Button Use Togle Button			LeftController Tag Untagged Untagged Controller Events Scale WITE_Controller Events Scale Controller Events Scale Scale Controller Events Scale	× 0 Y 2 × 0 Y 0 x × 1 Y 1 x VETK_CantralleEvents Texchad Press Texchad Press Texchad Press Trigger Press Trigger Press Texchad Press Texchad Press	2 0 2 0 2 1 2 1 2 1 0 0 0 0
PolphController Tog Umagged Polation Polition Rotation Scale VVTE_Controller Events (Script Scale VVTE_Controller Events Script Action Allas Stutton Pointer Togle Button Pointer Set Button Use Toggle Button Use Toggle Button Menu Toggle Button Axis Exfigurement Axis Exfigurement			Controller Tag Luftsgad Luftsgad Canasform Position Scale Cutom Alias Buttons Pointer Toggle Button Grab Toggle Button Ui Clock Button	× 0 Y 2 × 0 Y 0 Y × 1 Y 1 Y VETK_ControllerFounts Teachard Press Teachard Press Teachard Press Trigger Press Trigger Press Teachard Press Teachard Press	
BightController Togo Ustaged Controller Togo Scale VorteController Events (Script Scale VorteController Events (Script Compt Action Alias Buttons Pointer Cost Button Vorte Togole Button Vorte Togole Button Use Togole Button Use Togole Button Use Togole Button Menu Togole Button Avis Befinement Axis Refinement Axis Refinement Axis Refinement	1 Layer: Default X (0 Y (2 Z (0) X (0 Y (0 Z (0) X (1 Y (1 Z (1) X (1 Y (1 Z (1) Y (1 Z (1) VPTK, Controller@vonts Touckpad Press Touckpad Press Touckpad Press Touckpad Press Some Two Press		LaftController Tag Lutesgad Latesgad Latesgad Valia Controller Events (Scrip Script Action Alias Buttons Pointer Togle Button Grab Togle Button Ule Togle Button Ule Togle Button Ule Togle Button Menu Togle Button Aus Fidelity Trogler Clock Threahold	X 0 Y 2 X 0 Y 2 X 0 Y 0 X 1 Y 1 VETK_ControllerEvents Texchad Press Texchad Press Trigger Press Trigger Press Button Tuo Press 1 1	
PolphController Tog Umagged Polation Polition Rotation Scale VVTE_Controller Events (Script Scale VVTE_Controller Events Script Action Allas Stutton Pointer Togle Button Pointer Set Button Use Toggle Button Use Toggle Button Menu Toggle Button Axis Exfigurement Axis Exfigurement			LeftController Tag Lutraged Lotaged Lotaged Value Controller Events Controller Controller Events Controller Controller Controlle	X 0 Y2 X 0 Y0 X 1 Y1 VETX_ControllerEvents Teached Press Teached Press Trigger Press Trigger Press Ratten Tus Press Latten Tus Press 1	
RightController Tog Untaged Volume Second Sec	1 Layer Default X 0 Y 2 Z 0 X 0 Y 0 Z 0 X 0 Y 0 Z 10 Y 1 Z 1 Y 1 Z 1 VPTK, ControllerEvents Truckpad Press Grop Press Trusper Press Button Two Press 1 1 0.01 1		LeftController Tag Lutaggad Lotaggad Lotaggad Lotaggad Controller Events Controller	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 X 0 Y2 X	
BightController Tog Ustaged Construction Position Rotation Rotation Scale Vorte_Controller Events (Script Script Action Allas Button Pointer Toggle Button Pointer Set Button Use Toggle Button Use Toggle Button Use Toggle Button Acta Button Acta Button Acta Button Asis Fiddely Trager Cock Threshold Trager Force Zero On Untouch			Laftcortvoller Tag Laftcortvoller Lataged Lataged Lataged Variaged	× 0 Y 2 × 0 Y 0 × 1 Y 1 VETK_ControllerEvents Teachad Press Trigger Press Trigger Press Trigger Press 1 1 0.01 1 1	
BightController Tog Laraged SightController Tog Laraged Vortestorm Position Rotation Scale Vortestorm Vortestorm Scale Vortestorm Controller Events (Script Sorget Action Allas Buttons Pointer Toggle Button Pointer Toggle Button Us Clack Button Menu Toggle Button Aus Endets Trigger Clack Threshold Trigger Aris Zero On Untouch Grip Aris Zero Threshold Grip Aris Zero Threshold Grip Aris Zero On Untouch	1 Layer Default X 0 Y 2 Z 0 X 0 Y 0 Z 0 X 0 Y 0 Z 0 Y 1 Z 1 Y 1 Z 1 VPTK, ControllerEvents Tracebyse Press Tracebyse Press Tracebyse Press Tracebyse Press Tracebyse Press Section Two Press I 1 0.01 0.01 0.01 0.01 0.01		LeftController Tag Lutaggad Lotaggad Lotaggad Lotaggad Controller Events Controller	X 0 Y2 X 0 Y0 X 1 Y 1 VETX_ControllerFounts Teachad Press Teachad Press Teachad Press Trigger Press Intern Tue Press Intern Tue Press Intern Tue Press Intern Tue Press Intern Tue Press	
BightController Tog Laraged Controller Toge Laraged Controller Toge Controller Controler Controller Controller Controller Controller			LeftController Tag Luttaged Lottaged Lottaged Lottaged Lottaged Controller Events Controller Contreler Controler Controler Contreler	× 0 Y 2 × 0 Y 0 × 1 Y 1 VETK_ControllerEvents Teachad Press Trigger Press Trigger Press Trigger Press 1 1 0.01 1 1	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PiphtController Construction Construction	1 Layer Default X 0 Y 2 Z 0 X 0 Y 0 Z 0 X 0 Y 0 Z 0 Y 1 Z 1 Y 1 Z 1 VPTK, ControllerEvents Tracebyse Press Tracebyse Press Tracebyse Press Tracebyse Press Tracebyse Press Section Two Press I 1 0.01 0.01 0.01 0.01 0.01		LeftController Tag Lintaged Longed Longed Lintaged Longed Longed Controller Events (Scrip Sorget Action Alias Buttons Pointer Toggle Button Pointer Set Button Grab Toggle Button Ui Click Button Ui Click Button Mais Fidelity Trogger Click Threshold Trogger Force Zero Threshold Trogger Aris Zero On Untouch Ginp Force Zero Threshold Ginp Forc	X 0 Y2 X 0 Y	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
BightController Tog Laraged Controller Toge Laraged Controller Toge Controller Controler Controller Controller Controller Controller	1 Layer: Default X 0 Y 2 Z 0 X 0 Z 0 X 0 Z 0 X 0 Z 0 Y 1 Z 1 VETK: ControllerEvents Trackpad Press Trackpad Press Trackpad Press Trackpad Press Trager Press Second Tes Press I 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1 0.01 1		Laftcortvoller Tag Laftcortvoller Lataged Lataged Lataged Lataged Lataged Construction Position Position Position Scale V VIT_Controller Events (Scrip Songe Action Alas Buttons Pointer Set Button Pointer Set Button Pointer Set Button Use Taggle Button Destation Narker Settings Tagle Taggle Destation	X 0 Y2 X 0 Y2 X 0 Y0 X 1 Y 1 VBTK_ControllerEvents Teachad Press Trager Press Trigger Press Trigger Press I 1 0 0 VBTK_Pointer VBTK_Pointer	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
BiphtController Tog Linasged Vorte_Controller Tog Linasged Vorte_Controller Position Rotation Scale Vorte_Controller Events (Script Sorget Action Allas Buttons Pointer Togule Button Pointer Togule Button Use Toggle Button Use Toggle Button Asis FideButton Actis Refinement Axis Refinement Axis Refinement Axis StateSutton Trigger Cick Threshold Trigger Cick Threshold Trigger Cick Threshold Trigger Axis Zero On Untouch Grip Axis Zero On Untouch Trigget Fonce Zero Threshold Grip Axis Zero On Untouch Togget Destination Marker Settings Enable Teleport Target List Policy			LeftController Tag Lintaged Longed Longed Lintaged Longed Longed Controller Events (Scrip Sorget Action Alias Buttons Pointer Toggle Button Pointer Set Button Grab Toggle Button Ui Click Button Ui Click Button Mais Fidelity Trogger Click Threshold Trogger Force Zero Threshold Trogger Aris Zero On Untouch Ginp Force Zero Threshold Ginp Forc	X 0 Y2 X 0 Y	
PiphtController Too Ustaged Controller Too Ustaged Controller Too Ustaged Controller Pointer Controller Controler Controller Controller Controller Controller			Laftcortvoller Tag Laftcortvoller Lataged Lataged Lataged Lataged Lataged Construction Position Position Position Scale Action Alias Buttons Pointer Togels Button Pointer Set Button Use Togels Button Auis Fidelity Toger Clock Threshold Trigger Face Zero Threshold Trigger Face Zero Threshold Grip Clock Threshold Grip Clock Threshold Grip Asis Zero O Untouch Grip Elegort Destination Marker Settings Enable Telegort Target List Policy Pointer Activation Settings Pointer Rederer	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y0 X 1 Y 1 VETK_ControllerEvents Teachad Press Teachad Press Trigger Press Trigger Press Trigger Press Trigger Press 1 1 0.01 VETK_Policy List) LeftController (VETK_Straig)	1 2 0 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PaphtController Too Ustaged Controller Too Ustaged Controller Too Ustaged Controller Pointer Controller Controle Controller Controller Controller Controller			Laftcortvoller Tag Loftcortvoller Longard Longard Longard Longard Longard Constant Position Position Position Position Scale Controller Events (Scrip Scale Controller Events Controller Contro	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 1 Y1 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	
PiphtController Construction Construction			LeftConvoller Tag LoftConvoller Tag LoftConvoller Lonstorm Position Position Position Scale Gravity Controller Events (Scrip Scale Convolution Convolutio	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 X 0 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	1 2 0 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
BightController Tog Laraged Seget Seget			Laftcortvoller Tag Laftcortvoller Tag Laftcortvoller Lanstorm Position Position Position Scale Controller Events (Scrip Scale Controller Events (Scrip Scale Controller Events Script Controller Events Controller Events Scale Controller Events Script Controller Events Controller Events Controller Controler Contr	X 0 Y2 X 0 Y2 X 0 Y0 X 1 Y 1 VETX_ControllerFormts Teachad Press Teachad Press TriggerPress Intern Tuo Press Intern Tuo Press Intern Tuo Press VETX_Point VETX_Pointer VETX_Pointer VETX_Pointer LaftController (VETX_Straig) Tochad Press International Press Internati	1 2 0 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PiphtController Construction Construction			Laftcorboller Tag Laftcorboller Lataged Lataged Lataged Lataged Lataged Consoler Rectaion Scale Action Alias Buttons Pointer Togele Button Pointer Set Button Grab Togele Button Use Togele Button Wentry Togere Cleck Threshold Trigger Face Zero Threshold Grip Asis Zero On Untouch Grip Cleck Threshold Grip Asis Zero On Untouch Grip Asis Zero On Untouch Grip Asis Zero On Untouch Target List Policy Pointer Activation Settings Pointer Activation Settings Pointer Redefere Adivation Button Adivation Delay Pointer Selection Settings	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 1 Y 1 VETX_ControllerEvents Teachad Press Trappe Press Trigge Press Trigge Press Trigge Press Trigge Press 1 1 0.01 VETX_Policy List VETX_Policy List LeftCottroller (VETX_Straig) Teachad Press 0 0	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PaphtController Too Ustaged Controller Too Ustaged Controller Too Ustaged Controller Controler Controller Controller Controlle			Laftcorboller Tag Laftcorboller Tag Laftcorboller Lataged Lataged Lataged Construction Position Position Position Scale Action Alias Buttons Pointer Togele Button Pointer Set Buton Use Tragele Button Use Tragele Duton Trage Timeshold Grip Asis Zero On Untouch Target List Policy Pointer Activation Settings Pointer Rederer Adivation Button Adivate Activation Delay Pointer Selection Settings Bieldic Button Selection Sutton Selection Press	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 X 0 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	1 2 0 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
BiphEcentroller Tog Linasged Jord Linasged Jord Linasged Jord Linasged Vorte Vorte			LiftConvoller Tag LiftConvoller Tag LiftConvoller Lintagged LiftConvoller Lintagged Convolution Scale Gravity Gravity Convolution Con	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PiphtController Toge Lanaged Songe Action Allas Buttons Pointer Toge Button Pointer Toge Button Pointer Toge Button Pointer Toge Button Use Toggle Ruton Asis Fideenment Axis Fided Togger Cick Threshold Tingger Force Torreshold Tingger Force Torreshold Tingger Force Torres Use Toggle Button Asis Fided Tingger Cick Threshold Tingger Force Torreshold Tingger Force Torreshold Tingger Lisk Policer Use Toggle Denter Selection Marker Settings Pointer Renderer Adivision Button Hold Button To Activate Activation Oclay Pointer Selection Settings Selection Dress Selection Dress Selection Dress Selection Drelay Selection Polay Selection Polay Selection Polay			Laftcorboller To Lintcorboller Lintaged Lintaged Lintaged Lintaged Lintaged Lintaged Construction Scale More and a second	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 1 Y 1 VBTK_ControllerEvents Teached Press TriggerPress Dutton Two Press I 1 0 0 VBTK_Policy List VBTK_Policy List LeftController (VRTK_Policy List) LeftController (VRTK_Straig) Teached Press 0 0 Teached Press 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PiphtController Toge (Integed Toge (Integed Togetaged Togetaged Togetaged Togetaged Songet Action Allas Buttons Ponter Togetagetagetagetagetagetagetagetagetageta			LiftCortvoller Tag LiftCortvoller Tag LiftCortvoller Lansged Construction Position	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PaphtController Tog Literaged Tog Literaged Tog Literaged Toge Literage Toge Tog			Laftcorboller To Lintcorboller Lintaged Lintaged Lintaged Lintaged Lintaged Lintaged Construction Scale More and a second	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	1 2 0 2 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0
PiphtController Tog (Integed Togg(Integed Togg(Integed Togg(Integed Togg(Integed) Togg(Inte			Laftcarboller Tag Laftcarboller Lansform Position Position Position Position Position Scale Castform Position Scale Castform Pointer Set Button Pointer Set Button Pointer Set Button Ucital Button Pointer Set Button Ucital Button Ucital Button Vier Togele Button Ucital Button Ucital Button Vier Togele Button Ucital Button Vier Togele Button Ucital Button Vier Togele Button Vier Togele Button Ucital Button Vier Togele Bu	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	1 2 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1
PiphtController Toge Lanaged State St			Laftcarboller Tag Laftcarboller Lataged Lataged Lataged Lataged Lataged Lataged Caster Action Altas Buttons Scale Action Altas Buttons Pointer Togle Button Pointer Togle Button Use Toggle Button Select On Plays Select Alter Hover Duration Painter Toge Painter Tog Pointer Customisation Settings Indens Utho Open Select On Plays Sel	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 1 Y 1 Y 1 Y 1 Y 1 Y 1 Y 1 Y 1 Y	2 (6) 2 (6) 2 (1) 0 1
PiphtController Tog Untaged Controller Tog Untaged Controller Toget Controller			Laftcarboller Tag Laftcarboller Lansform Position Position Position Position Position Scale Castform Position Scale Castform Pointer Set Button Pointer Set Button Pointer Set Button Ucital Button Pointer Set Button Ucital Button Ucital Button Vier Togele Button Ucital Button Ucital Button Vier Togele Button Ucital Button Vier Togele Button Ucital Button Vier Togele Button Vier Togele Button Ucital Button Vier Togele Bu	X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 X 0 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2 Y2	1 2 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1

Figure 3-14-1 Setting the headset and controllers.

Only if the headset and controllers are set, the virtual environment can be connected with HTC Vive, and the user can use controllers to do the interaction. After that, the clicking button function will be described in the virtual environment with HTC Vive.

The function in VR - Building Canvas in the virtual environment and using the controller to click the button.



Firstly, Building Canvas in VR - Figure 3-14-2

Figure 3-14-2 The vital points about establishing the Canvas in VR.

Canvas is the indispensable part to achieve the button function. In VR, the key point is to change the Canvas in world space state.

Secondly, understanding the using function of the controller. Figure 3-14-3

🐔 🗹 VRTK_Straight Pointer Renderer ((Script)		SYSDIA SOLUTIONS LTD
Script	VRTK_StraightPointerRenderer	O YOK	VRTK - Virtual Reality FREE
Renderer Supplement Settings			Toolkit - [VR Toolkit] Add to My Assets
Playarea Cursor	None (VRTK_Play Area Cursor)	0	182 uper reviews
Direction Indicator	None (VRTK_Pointer Direction Indicator)		The user reviews
General Renderer Settings			Popular Taga
Custom Raycast	None (VRTK_Custom Raycast)	 wrtual reality toolet 	Add a new tag right now?
Layers To Ignore	Ignore Raycast	1 "Interior"	Add tags
Pointer Origin Smoothing Settings		VR ESSENTIALS	
General Appearance Settings Valid Collision Color Invalid Collision Color			The SDK Manager was updated in 3.2.0 - Any scenes using the old SDK Manager set up will need to be updated. Watch this video from 5:36 time stamp for more details ->
Tracer Visibility	On When Active	+26	https://www.youtube.com/watch? v=tvFV9o8Reap&feature=voutu.be&t=334
Cursor Visibility	On When Active	•	v=tyFv300Heggaredsure=youtu.beat=334
Straight Pointer Appearance Settings			
Maximum Length	100		
Scale Factor	0.002		
Cursor Scale Multiplier	25		
Cursor Match Target Rotation			
Cursor Distance Rescale			
Maximum Cursor Scale	X Infinity Y Infinity Z Infinity		
Straight Pointer Custom Appearance S			
Custom Tracer	None (Game Object)	•	
Custom Cursor	None (Game Object)	•	

Figure 3-14-3 The function of the controller.

Figure 3-14-4 Plugin - VR Toolkit.

The function of the controller can be built by a Plugin called VRTK - VR Toolkit. It is a useful plugin to achieve the button function in VR. Figure 3-14-4 VRTK - VR Toolkit

https://assetstore.unity.com/packages/tools/vrtk-virtual-reality-toolkit-vr-toolkit-64131

Also, the clicking button scripting is also needed to be fixed. Figure 3-14-5 The scripting of button clicking. Figure 3-14-6 Arranging the scripting on the specific button.

"Button_Onclick(){}" is the essential function of the scripting.

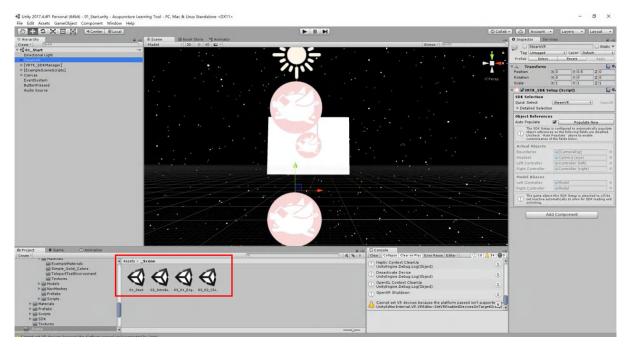
```
1 using System.Collections;
2 using System.Collections.Generic;
   3 using UnityEngine;
  4 using UnityEngine.UI;
  6 public class NextButton01 : MonoBehaviour {
         // Use this for initialization
public GameObject false01;
public GameObject false02;
  8
 10
 11
         public GameObject false03;
 13
 14
         public GameObject true01;
 15
         public GameObject true02;
 16
 17
         //public GameObject true03;
 18
19
        // Use this for initialization
void Start () {
 20
 21
         3
 23
 24
         public void Button_Onclick(){
 25
 26
              false01.SetActive (false);
 27
              false02.SetActive (false);
 28
              false03.SetActive (false);
 29
 30
              true01.SetActive (true);
 31
              true02.SetActive (true);
 32
              //true03.SetActive (true);
 33
 34
 35
36
         }
 37
         // Update is called once per frame
 38
         void Update () {
 39
 40
         }
 41 }
 42
```

Figure 3-14-5 The scripting of button clicking.

🖰 🕂 S 💢 🔟 🏵 🔍 Center	@Local			Collab • 🛆 Account • Layers • Layout
reste - forAll ♥ Usacupoint_anatomy ♥ Patient 01 shoulder_new ▶ Head ▶ Hand	- # Soote Asset Store & Anima Skelet - 20 & 0 = -	Gonu * (74)	O Inspector Bervices Material Raycast Target Image Type Preserve Aspect	None (Material) Simple Statistics Size
		*		Cene Test Gene Test Generation (image)
<pre>% Yesinovas, stde Tide_image Tide_image (1) ScoreBeard_std Frankel_ent Frankel_std Col_type of readel Col_type of Col_type Col_type of Col_type Col_type Col_type of Col_type Col_type Col_type of Col_type Col_t</pre>		·继续 NEXT	On Clok () Persia Only 2 (*Restdenciol (Nextslater) (*Restdenciol (Nextslater) (*Restdenciol (Nextslater) Default UI Material Shader UI Ortsat NextBitten03	Visualize Visual
A ADUL Juniedie feelbaks Vroject € Came O Amenadol en reactuis en	Austra Stene	Control Contro Control Control Control Control Control Co	1 1 1 1 form page (SendMessage (sing) SendMessage(burst) StopAlCoroutine () StopAlCoroutine (string) NEXT

Figure 3-14-6 Arranging the scripting on the specific button.

3.2.5.2 Implementing Virtual Environment



Firstly, the prototype of the application has four scenes. Figure 3-15-1

Figure 3-15-1 The prototype of the application has four scenes. Start; Introduction;

English acupuncture training; Chinese Acupuncture training.

Secondly, the virtual environment will be established. The first step, the designer needs to find a suitable position to arrange the VR camera. Figure 3-15-2. The second step, organize the suitable models in the virtual environment. Table 3-9-2.



Figure 3-15-2 Arranging the VR camera.

Table 3-9-2 shows that the models used within the virtual environment consist of open resources which were bought to online UNITY ASSET STORE.

Model Information	Description	Reference
Doctor's Office	Models have many	The model could be
	hospital elements can be	bought to online UNITY
	used to build an	ASSET STORE; the
	acupuncture clinic.	following is the online
	Figure: 3-15-3	address.
		https://assetstore.unity.co
		m/packages/3d/props/inter
		ior/hospital-doctor-s-office-
		<u>65226</u>

Table 3-9-2 Illustrating the information of models and reference.



Figure 3-15- 3 Doctor's Office models (UNITY ASSET STORE, 2017).

Thirdly, in the virtual environment, the animation tips about the acupoint is also an element in the virtual environment. Figure 3-15-4. The animation tips cannot only remind the user about the position of the acupoint but also add interest to the application.

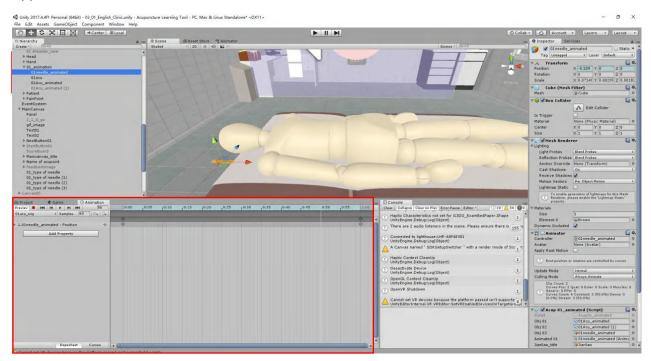


Figure 3-15-4 The animation tip on the brown needle.

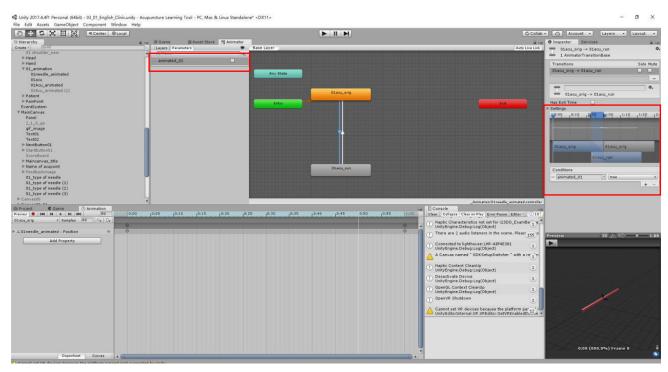


Figure 3-15-5 The animator on the brown needle.

Figure 3-15-5 shows the animator on the needle. The animator uses the bool function, and it is useful for the designer to use the animation on scripting. If the designer wants to run the animation, will use "animated_01 = true".

Finally, scripting to make the process of operating smoothly is also a mentionable point in the virtual environment.

In the application, "How to run many elements in order?" is confused the designer. The method to arrange many elements is using the function "IEnumerator(){}." Figure 3-15-6.

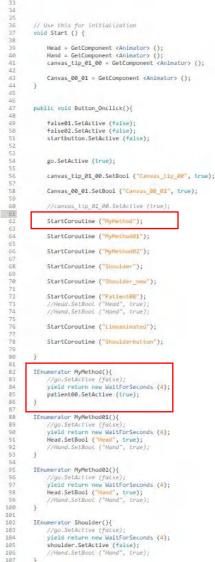


Figure 3-15-6 The scripting to make many elements in the application run in order.

In the application, the scripting means the current operation will wait a few seconds. The designer can change the waiting seconds to arrange the different operation in order.

3.2.6 Haptic Interaction

In this part, the programming about the accurate feedback platform will be explained detailedly. Besides, the feedback prototype with the haptic device will be implemented.

3.2.6.1 Programming of the Application in Haptic Interaction

To achieving the real-time feedback platform, first of all, the rationale of the Plugin need to be understood. A suitable needle model should be connected with the Plugin; it will move the position and rotate followed the haptic device. Figure 3-16-1 Figure 3-16-2 Figure 3-16-3.

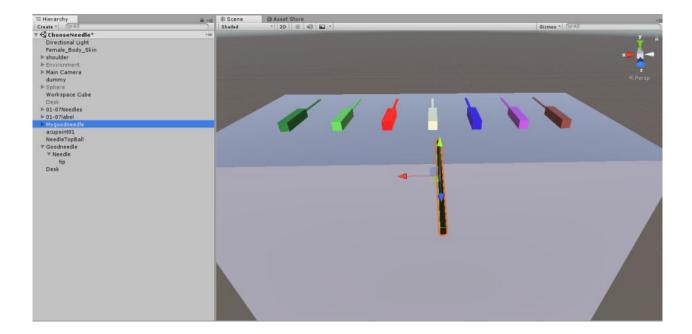


Figure 3-16-1 shows "MygoodNeedle" in the environment.

Inspector Services dummy					- C Statio	-
		↓ Layer Default +				
		• Layer	Delaute			
Transform	111					\$
Position	X 0		0		0	_
Rotation	X 0		0	1.72	0	_
Scale	X 1)	1	Z	1	
T 🚱 Generic Functions C		and the second se				*
Script	C G	SenericFunctions	sClass			0
My Haptic Class Script	@ d	ummy (Simples	ShapeMan	ipulationA	AndPhysics)	0
🔻 健 🗹 Simple Shape Manip	ulation A	And Physics (S	Script)			\$
Script	0/5	impleShapeMar	nipulation/	AndPhysic	S	0
Haptic Mode						
Mode Index	1					
Touchable Face	front					
Device 1 Name						
My Haptic Camera	() H	laptic Camera				0
Work Space Obj	Workspace Cube				0	
Haptic Cursor	@Mygoodneedle				0	
My Work Space Position						
Size	3					
Element 0	1					
Element 1	2					
Element 2	0					
▼ My Work Space Size						
Size	3					
Element 0	2					
Element 1	2					
Element 2	2					
Device 2 Name						
My Second Haptic Camera	Nor	ne (Game Objec	t)			0
Second Work Space Obj	Nor	ne (Game Objec	t)			0
Second Haptic Cursor	None (Game Object)					0

Figure 3-16-2 shows the excellent needle model has been connected with the haptic



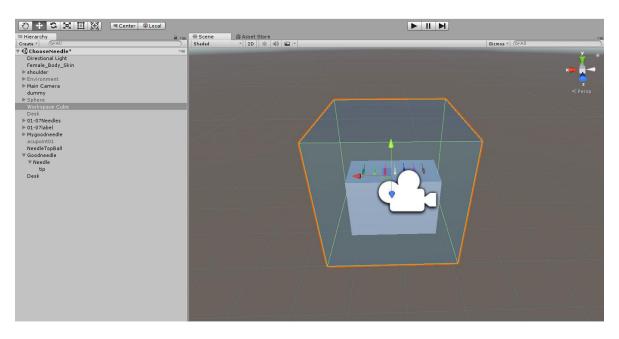


Figure 3-16-3 shows the moving space of the haptic device.

After fixing the fundamental haptic plugin, three main scripting in the feedback platform will be mentioned.

1. The first function - scripting the choosing needle function and understanding the use of buttons on Phantom Omni.

Firstly, the choosing needle scripting is based on the function "OnTriggerEnter(){}" and "OnTriggerExit(){}". Figure 3-16-4



Figure 3-16-4 The scripting achieves the collision detection. "OnTriggerEnter" means the device touches the needle model. "OnTriggerExit" means the device leaves the needle model.

In the scripting, the haptic device can get collision detection, and make the relevant response. In the application when the haptic device touches the needle model, the needle introduction will be shown. Figure 3-16-5



Figure 3-16-5 The function prototype of choosing the relative needle.

Secondly, understanding the use of buttons on Phantom Omni can achieve the needle chosen the correct color. It means "MygoodNeedle" can change the color when the user clicks the button to Phantom Omni. Figure 3-16-6 Figure 3-16-7 Figure 3-16-8

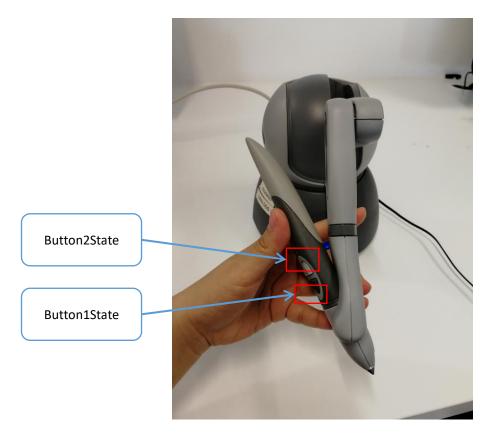


Figure 3-16-6 shows the two buttons on the haptic device.



Figure 3-16-7 shows the scripting about using the button to change the color. "GetButton1State(){}" is a bool function to activate the using of the Button1 on the haptic device.

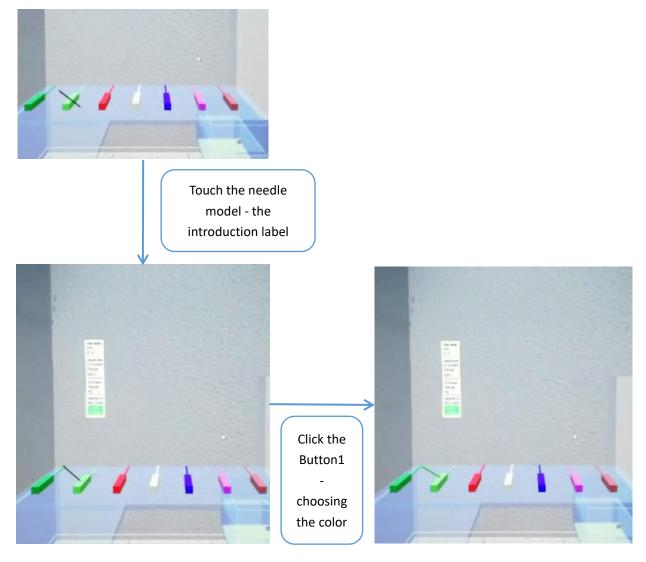


Figure 3-16-8 shows the prototype of the choosing needles.

2. The second function - Real-time feedback.

The core of the function is the application of the Render Texture. Figure 3-16-9 shows the step achieving the real-time feedback.

Firstly, creating a render texture in assets.

Secondly, creating a camera to target the position where needs the real-time feedback, and fix the render texture under the camera.

Thirdly, showing the render texture on Canvas.

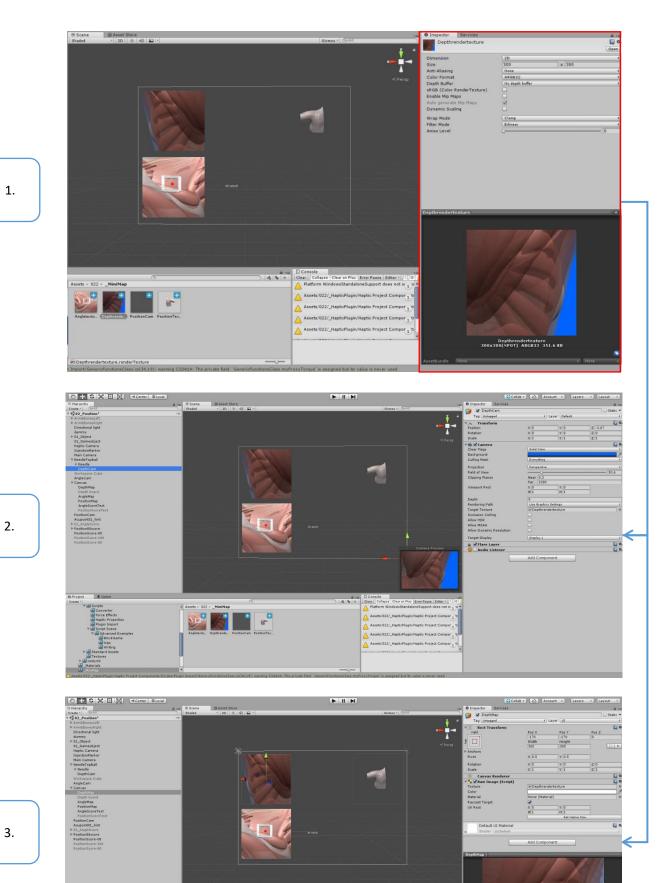


Figure 3-16-9 The process of creating the real-time feedback texture on Canvas.

Assets + 022 + _MiniMap Assets + 022 + _MiniMap Assets - Deptersde PesitiseCan PesitiseTex. 3. The third function - Recording the terminal feedback on the scoreboard.

The function can be divided into two parts, the first is recording the feedback texture, and the second is showing the recorder on Canvas.

Firstly, the scripting of saving the texture to a fixed path. Figure 3-16-10 Figure 3-16-11

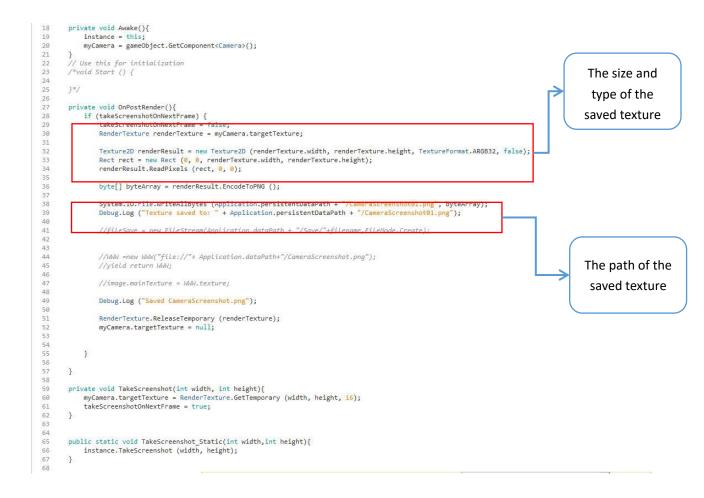


Figure 3-16-10 shows the size, type, and path of the saving texture.

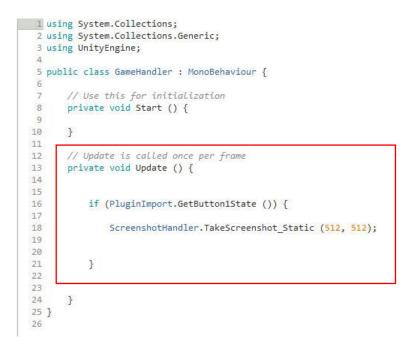


Figure 3-16-11 shows pressing the Button2 on the haptic device and then the texture saved.

Secondly, creating a new image on Canvas to load the saved texture. Figure 3-16-12 Figure 3-16-13



Figure 3-16-12 shows the scripting of loading the saved texture from the fixed path.

20 2. perito ** Armadianestadia ** Armadianestadia ** Bestadia ** Bestadia ** Bestadia ** Angletica ** Angletica ** Angletica ** Angletica ** Angletica ** Angletica ** Peritoria ** Angletica ** Peritoria **	Calor Revision Revisi	001 ed	es Y Pes Z 70 0 eleight 0.5 0 Z 0 1 Z 1
A control of the second light mmy Gene ArgeAdag Caseada ArgeAdag Caseada ArgeAdag Caseada ArgeAdag Caseada Caseadaa Caseadaa Caseadaa Caseadaa Caseadaa C	Tra Uman Tra	ed	UI 00 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
middouestaft dearbordight Carroni Ca	Tag Lunae	ed	es Y Pes Z 70 0 eleight 0.5 0 Z 0 1 Z 1
makenasight: executed light provides and lig	Repart Target	Pis X Pis X Width N Width N Width N Width N X (5.5 Y X (1 Y X (1 Y X (1 Y Script) Confectors None (Sprite) None (Sprite) None (Sprite) None (Sprite) With Advantal V	70 0 feight 00 2 0 1 2 1
Addad market Object	Repart Target	Pis X Pis X Width N Width N Width N Width N X (5.5 Y X (1 Y X (1 Y X (1 Y Script) Confectors None (Sprite) None (Sprite) None (Sprite) None (Sprite) With Advantal V	70 0 feight 00 2 0 1 2 1
Object dic Carrers dic Carrers discrete Harac Cube Harac Cube	Anchers Rivet Potation Scale Societ My Image Color Referind Revicat Target	Width H x (0.5 Y y (0.5 Y	eight 000 05 0 2 0 1 2 1
Gancebjett Scolare i Scolare i	Anchers Rivet Potation Scale Societ My Image Color Referind Revicat Target	100 1 × (0.5 Y × (0.5 <td< td=""><td>0.5 0.5 1 Z 0 1 Z 1</td></td<>	0.5 0.5 1 Z 0 1 Z 1
tic Canner Marsen Cale Marsen	Anchers Protein Scale Sc	X (0.5 Y X (0.5 Y X (0.5 Y) X (0.5 Y	0.5 0 Z 0 1 Z 1
ts care Cube We can set Set Set Set Set Set Set Set Set Set S	Pivet Relation Scale Cenves Color Leader Hylmage Celor Repeat Target Default	X G Y X S Y Y X S Y Y Y X S Y X S Y Y Y Y	0 Z 0 1 Z 1
dd ropabl Kasan Cula Kasan C	Soak	X G Y Y Randerer stater (Script) Coaffecture Script) None (Sprite) None (Sprite) UN Material UN Defest	0 Z 0 1 Z 1
Nagana Culas Services Se	Soak	x 1 y Renderer stare (Script) Script) Scripts Script) None (Sprite) None (Sprite) None (Material) UMaterial Scripts	1 Z 1
et in the second	Carvas Sorta Mirman Surtan Surtan Surtan Surtan Surtan Revisit Parystat Targan Dafault	Renderer sture (Script) Script) None (Sprite) None (Sprite) None (Material) t UNDaterial UDDatest	
et Staare et Staare et Staare V Advance E za piz U Bockare U Bockare V Advance E za piz U Bockare U Bo	Calor Revision Revisi	store (Script) Script) None (Sprite) None (Material) UI Material UI Dafaat)
etch bard d might bard d package for the	Sont My Image Surve Truge Color Material Reycat Torup Default	Script) None (Sprite) None (Material) t UI Material UD Defeat	
ngeldage nge	He Image	Correct01 (Image Script) None (Sprite) None (Material) UI Material UD Defailt	
di Came	Source Image Source Image Celer Meterial Parciat Targe Default	t UI Material UU Defeet	
ngleScare Text sourcestal martetal periodE.unit StandBader 400 for Control of	Source Image Color Material Raycast Targe Default	None (Sprite) None (Material) UI Material UI/Defrait	
der det and a set of	Material Raycast Target Default	t 🖌 🖌	
dar de 2 benefan de la companya de	Raycast Target Default	t 🖌 🖌	
spendb_heit BioshBiose Biosh	Default	UI Material	
t Came		U2/Default	
t Came	> Shader		
anticare 20 mer Source 20 mer Sour		Add Component	
t Come ***********************************		Add Component	
et et Game * Came * Asses - Example - Script - Doc Game * Doc Game	1		
t Came **** Assets - ExampleScript - (0. *********************************	112		
et © Game V 🖉 Advanced Ecouples BlockGame BlockGame Displosed Displosed Ecouples Displosed Ecouples			
et & Game * El Akonced Exe ples = t t t t t t t t t t t t t t t t t t t			
Assessed Examples Assessed Examples Assessed Examples Asse			
· VIII Advanced Exa price · Dioc Game · Dioc Game	the second s		
* W Advanced Examples _ script	Correct01 #		
Assets - Example - Script -			
Advanced Exe opter Acets - Example - Script - Biological	A +m Console +m		
	A & * Clear Collapse		
	Asset 1 *		
Writing	🚼 🔁 🔥 Asset 1 >>		
> Standard Assets C#	# C# 🛆 Asset 1">		
LinityVS texture AngleCollid AngleScore CameraRot FadeOut GameHandl HandChang Label LoadTexture He	edle PesitionColl. Asset 17		
Materials			
MiniMap Model	Asset 1		
Materials C# C# C# C# C#	Asset 1		
Plugin Import			
PositionSco Screen Screensho ShouDepth Tipchangec			
▶≝Room02			
Scene		Corr ict01 Image lize: 0x0	
		Image IZe: 0x0	
\mathbf{v}		¥	
	(
Creating an omnty		Fixing the loa	ading
Creating an empty			Juli B
imago on Canvas		scripting unde	er the
image on Canvas		scripting unue	
-)			
		image	
		iniuge	

Figure 3-16-13 shows the image on Canvas which shows the saved texture.

Create an image to load the saved texture on Canvas and fix the loading scripting under the image.

3.2.6.2 Implementing the Feedback Platform Prototype

The feedback platform is composed of the real-time feedback and recording the terminal feedback on Canvas. Figure 3-17-1 shows the real-time feedback prototype.

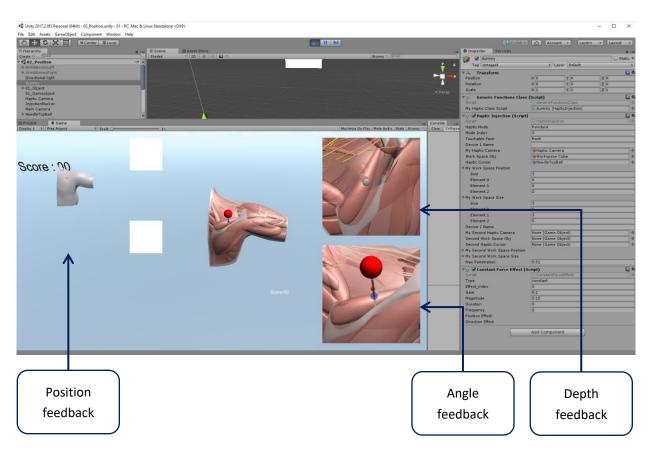


Figure 3-17-2 shows the saving and loading the terminal results.

Figure 3-17-1 shows the concurrent feedback, and reflect the real-time texture on Canvas; it includes the position of acupoint, the angle of the needle and the depth of needling.

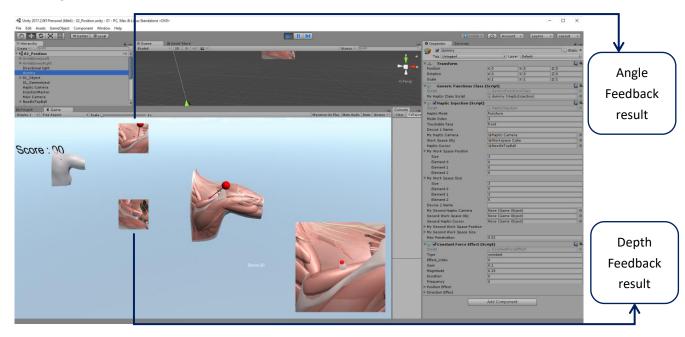


Figure 3-17-2 shows loading the saved texture on Canvas.

3.2.7 Final Design of the Application - Combining VR and Haptic

technology

In this part, the virtual and haptic technology will be combined in the development of the application. Figure 3-17-3 Figure 3-17-4

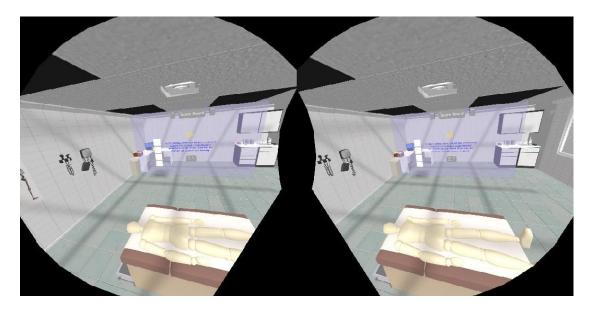


Figure 3-17-3 shows the environment of the application in HTC Vive.

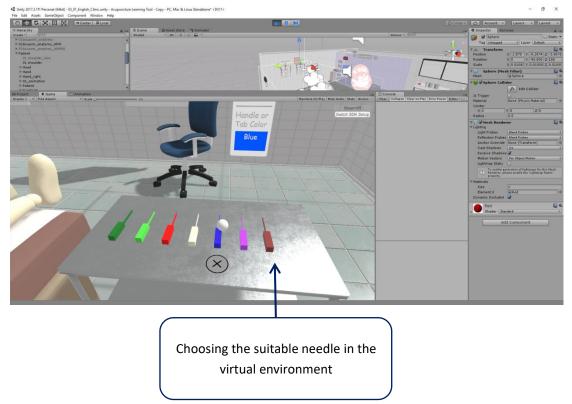


Figure 3-17-4 shows the haptic development in the virtual environment.

4 Results

In this part, the results of the application will be illustrated clearly. It contains the whole introduction animation, every scene of the application and the total training of acupuncture.

The application is a platform to provide the accurate feedback of acupuncture; it is developed by two devices, HTC Vive and Phantom Omni. The user can learn the rationale of acupuncture and train the needling skills on the application.

4.1 Introduction Animation

The introduction of the periarthritis of shoulder and the acupuncture will be arranged before the acupuncture training (as seen in Appendix 2). Figure 4-1 shows the animation images of the introduction of the periarthritis of shoulder run in the application. Figure 4-2 the introduction animation in VR. Figure 4-3 shows the animation images of the introduction of the acupuncture run in the application.



Figure 4-1 The animation images about the introduction of the periarthritis of shoulder.



Figure 4-2 The introduction animation in VR.

Click the Play Button

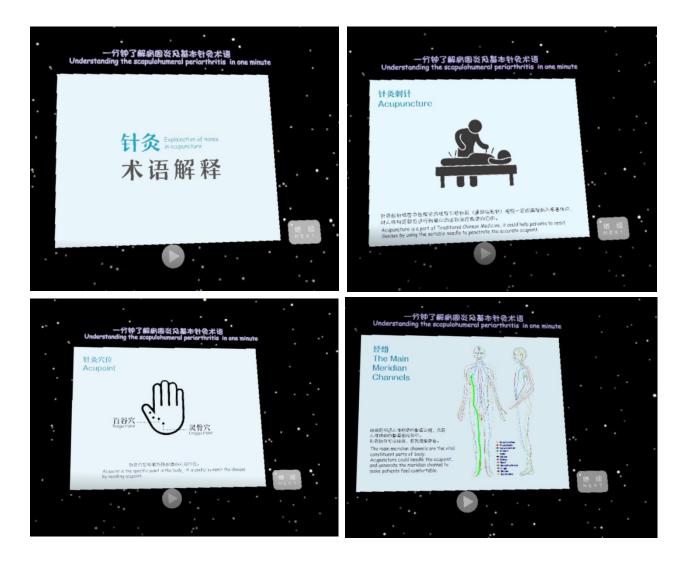


Figure 4-3 The animation images about the introduction of the acupuncture.

Because the acupuncture training is treating the periarthritis of shoulder, the introduction of the periarthritis of the shoulder is needed to understand before training.

"Acupuncture," "Acupoint," "The Main Meridian Channels" these three nouns are professional vocabularies in the acupuncture training. Therefore, the explanation of professional dictionaries is necessary for the introduction interface. It can help the user understand the knowledge of acupuncture better.

4.2 Application Results



4.2.1 Start and Introduction

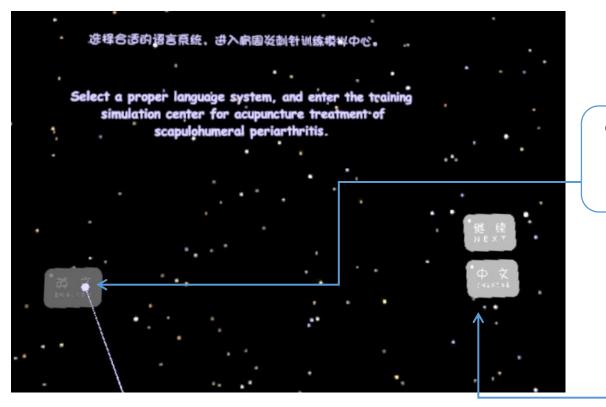
Figure 4-4 The start interface.



Figure 4-5 The introduction of the periarthritis of shoulder and the acupuncture.

Start

Introduction



Choosing a language, English or Chinese

Figure 4-6 Choosing a language to enter into the acupuncture training centre.

In the introduction interface, the user can choose a suitable language to run the needling training smoothly; the language text system is consistent with the audio system.

4.2.2 Accurate Needling Training

In the needling training scene, firstly, the animation and introduction will be shown in the virtual environment. Figures 4-7, 4-8, 4-9. Secondly, the user can run the acupuncture training followed by the hint animation of acupoint. Figure 4-10. Also, the real-time feedback of needling will be shown on the Canvas in the virtual environment. Figures 4-11, 4-12, 4-13, 4-14.



Figure 4-7 The introduction of acupuncture training centre.

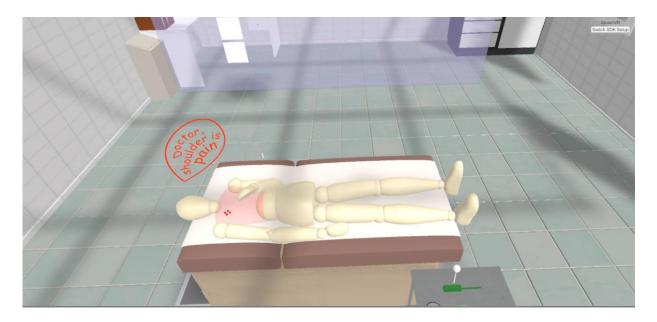


Figure 4-8 The animation of the disease.

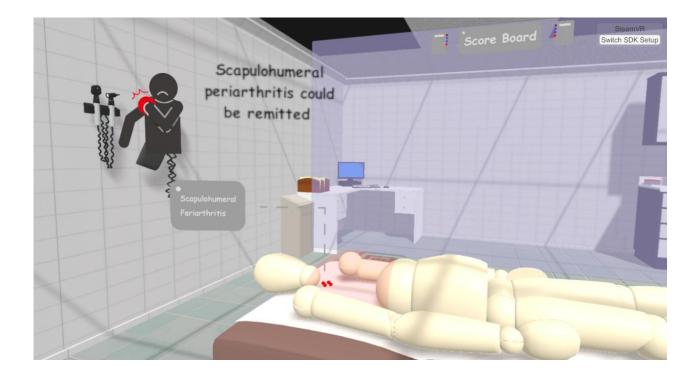


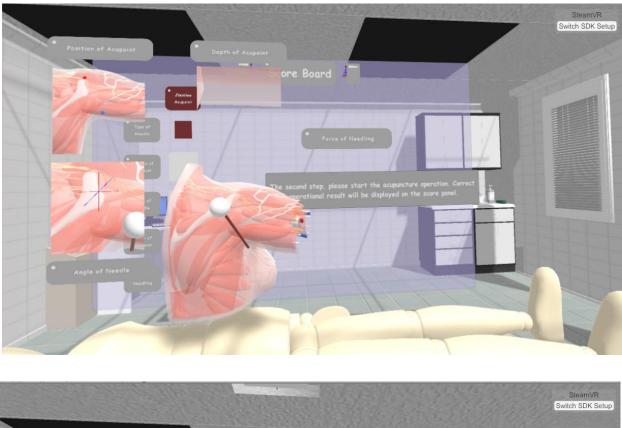
Figure 4-9 The introduction of the disease.



Figure 4-10 The hint animation of the acupoint.



Figure 4-11 The choosing needle operation and feedback.



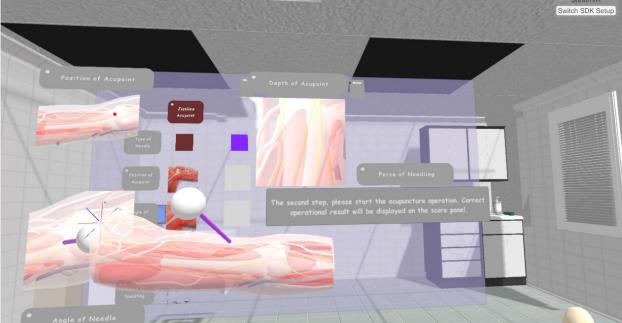


Figure 4-12 The concurrent operation and feedback about the needling

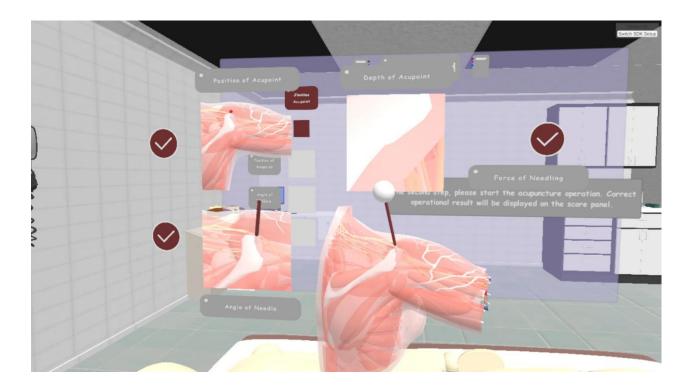


Figure 4-13 The real-time judgment with the operation (right label)

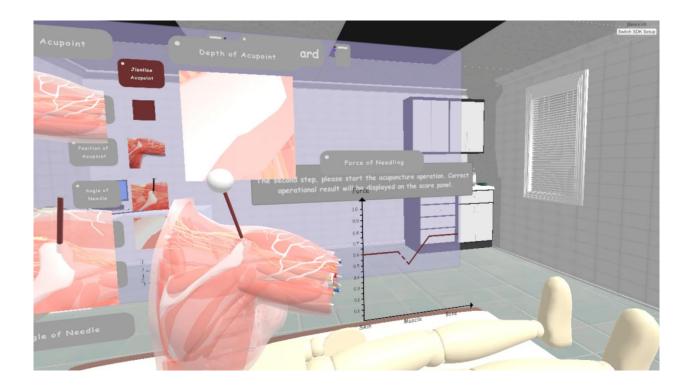


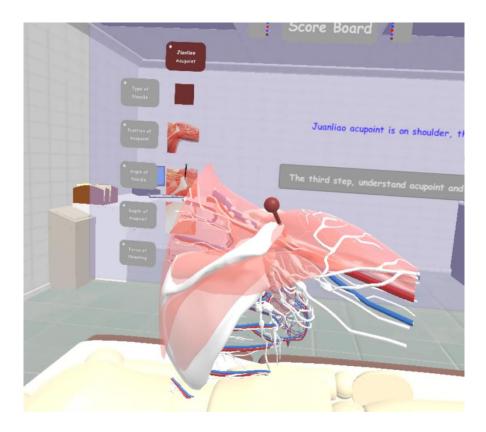
Figure 4-14 The force chart of the needling.

4.2.3 Terminal Needling Results

The user can record the needling result, when he or she achieves the total right labels, by pressing the Button2 on the haptic device. And the results will be shown on the scoreboard. Figure 4-15. Moreover, the anatomical animation will be shown to tell the user the correct operation and the relationship between the anatomy and acupuncture. Figure 4-16. After that, the user will see the running of the main meridian channels to remit the disease. Figure 4-17. Finally, the user can send the terminal results to the professional acupuncturist to get the expert evaluation and feedback. Figure 4-18.



Figure 4-15 The terminal results are shown on the scoreboard.



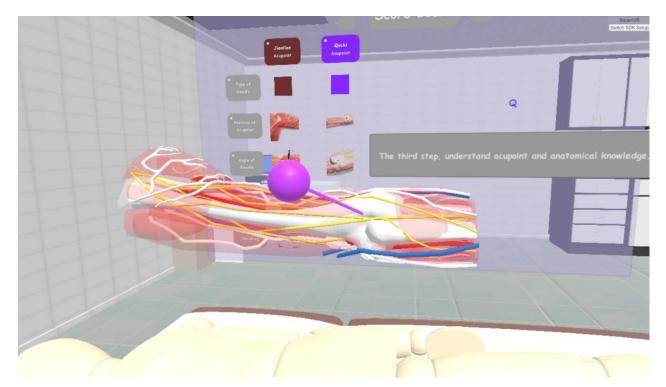


Figure 4-16 The correct needling and anatomical animation.



Figure 4-17 The main meridian channels to remit the disease.

	_		_		Ster
		Jianfico Acupoint	Quehi Acapoist	Score Board	111111
	Type of Needle Position of			You could send these image rsults to the professional acupuncurist and get a feedback.	
	Acupaint Angle of Needle		5	Send to the professional acupuncturist.	
9	Degth of Acupoint				
	Force of Needling		and a		
-			-		

Figure 4-18 Send the terminal images to the professional acupuncturist.

4.2.4 Acupuncture and Anatomy Learning

The user can learn the knowledge of acupuncture and anatomy by the introduction interface (Chapter 4.2.1), the audio tip (Figure 4-19), the acupoint hint (Chapter 4.2.2 Figure 4-10), the anatomical animation(Chapter 4.2.3 Figure 4-16) and the running of main meridian channels (Chapter 4.2.3 Figure 4-17).

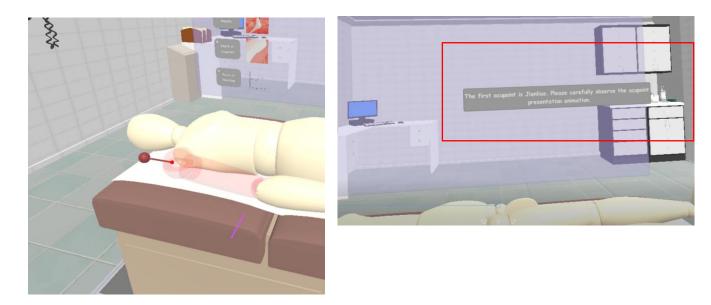


Figure 4-19 The audio tip of the steps in the acupuncture training.

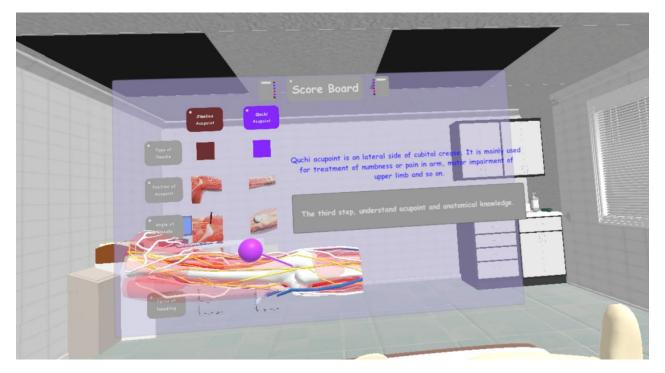
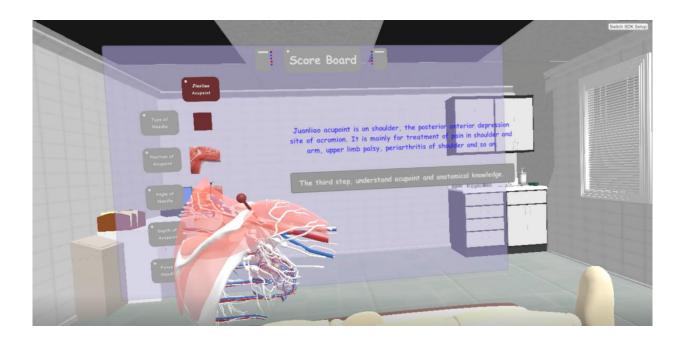


Figure 4-19-1 The audio tip of the introduction of the acupoint.

4.2.5 Languages System

The user can choose a suitable language to do the training. Figures 4-20, 4-21.



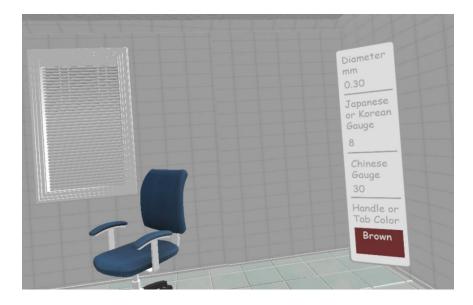


Figure 4- 20 The English System

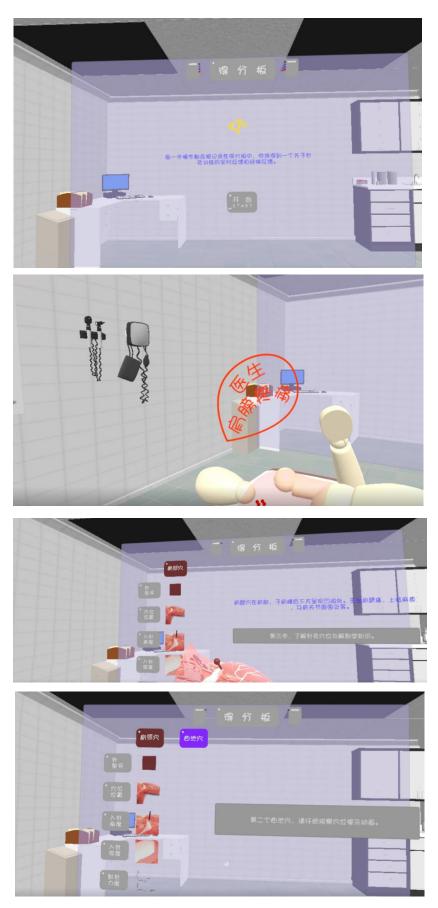


Figure 4- 21 The Chinese System

5 Evaluation

5.1 Introduction

It is necessary to test the application with the two groups of participants to access the usefulness and integrity of the feedback platform in the acupuncture. Participants will operate the whole application through HTC Vive and the haptic device. The initial hypothesis for testing is expecting the accurate acupuncture feedback can be achieved and the knowledge of acupuncture can be delivered. However, overall the application should be received well by all participants with the minor calibration to make the app more professional and competent.

5.2 Methods

5.2.1 Participants

A total of 10 people took part in the testing, eight students, and two acupuncturists. Two groups of participants were defined. The first group was composed of GSA students from the various courses. The second group was professional acupuncturists from the acupuncture stores in the UK. The acupuncturists would calibrate the parameter of haptics to make the haptic feedback realistically, and they completed questionnaires. It was worth highlighting that students paid more attention to the understanding and learning the knowledge of acupuncture, and the professional acupuncturists took part in the calibration of the haptic properties.

5.2.2 Experimental Set-up

The testing used the HTC Vive, Phantom Omni, and the suitable PC. During the experiment, the participants were sitting at the desk and wore the VR headset to connect with the virtual environment. Also, the haptic device was used to test the force feedback. Figure 5-1 The testing situation.



Figure 5-1 The testing situation

5.2.3 Procedures

5.2.3.1 Testing by the Professional Acupuncturist

Two professional acupuncturists were from the acupuncture stores in the UK, Shizhen Chinese Medicine Store and Chinese Medicine Centre 2000.

Firstly, the acupuncturist was placed in front of the PC with the VR headset and the haptic device positioned on the desk in front of them. At the beginning of the application, they watched the introduction animation to analysis the validity of the

information.

Secondly, entering into the acupuncture training centre, the information of the real-time training feedback was measured carefully.

Thirdly, the acupuncturist was asked to analyze the validity about the acupoint hint information and the anatomical animation. The acupuncturist would test the application from the professional, accurate and available angle to analysis the advantage and disadvantage of the application.

Finally, the acupuncturists would calibrate the haptic feedback in the acupuncture training. So they would help the application become more realistic and accurate.

5.2.3.2 Testing by the GSA Students

Universal testing aimed to evaluate the stability and usefulness of the application as the users did not have the previous acupuncture knowledge. Multi-angle evaluations would be obtained because the testing students were from the various courses in GSA. The users could do the review of the total application expression, delivering the knowledge of acupuncture, as well as what the students think could be developed into the application.

The students were also the essential participants in the testing because the application had an aim to deliver the knowledge of acupuncture to the next generation. Exploring the methods for spreading the acupuncture knowledge is meaningful.

5.2.3.3 Data Analysis

After testing the application, questionnaires were implemented by students and acupuncturists. Students were given the standard survey, and the acupuncturists had the professional one (as seen in Appendix 1).

Also, the questionnaire outcomes and data analysis were illustrated clearly in Chapter 5.3.2

5.3 Results

5.3.1 Calibration

T 🕞 Haptic Prope	rties (Script)	D \$.
Script	HapticProperties	0
Stiffness	0.2	
Damping	0.25	
Static Friction	0.02	
Dynamic Friction	0	
Tangential Stiffness	0	
Tangential Damping	0	
Pop Through	0.05	
Punctured Static Fric	t 0.6	
Punctured Dynamic F	0.96	
Mass	0	
Fixed Obj		

Figure 5-2 The needling feedback force across the skin.

Haptic Proper	ties (Script)	a .
Script	HapticProperties	O
Stiffness	0.18	
Damping	0.21	
Static Friction	0.02	
Dynamic Friction	0	
Tangential Stiffness	0	
Tangential Damping	0	
Pop Through	0.05	
Punctured Static Frict	ic 0.6	
Punctured Dynamic F	ri 0.96	
Mass	0	
Fixed Obj		

Figure 5-3 The needling feedback force across the muscle.

Above figures show the calibration of haptic properties, which adjusted by the acupuncturists.

5.3.2 Questionnaire Outcomes and Data Analysis

Firstly, the following charts show the students' understanding of acupuncture in standard questionnaires for GSA students. Charts 5-1, 5-2, 5-3, 5-4.

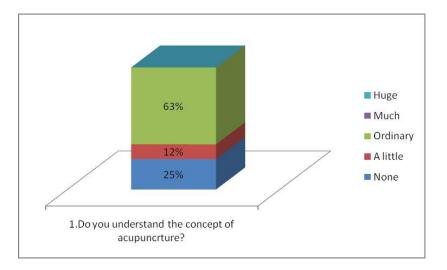
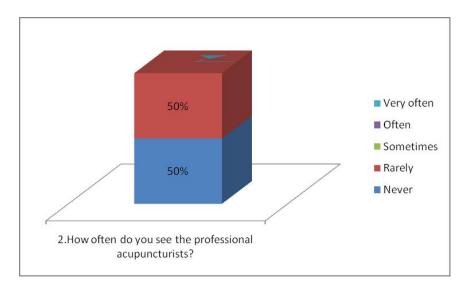
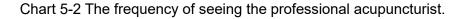


Chart 5-1 The understanding of the concept about the acupuncture for students.

The chart shows the students' original understanding of the acupuncture, and the most students have the collective knowledge about the acupuncture. However, they do not have the specific relevant understanding about acupuncture.





The chart shows the frequency of seeing the professional acupuncturist. It shows that acupuncture is an unpopular method for the young generation to do the treatment or health-care.

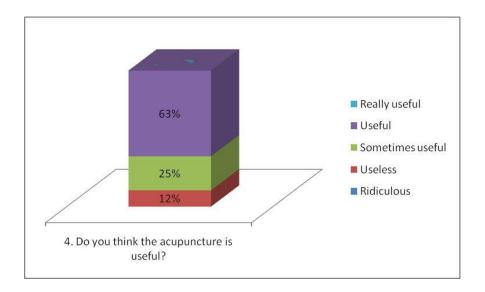


Chart 5-3 The reliability of the acupuncture.

The chart shows more than half students still think the acupuncture is useful. It means in the young generation, although they do not choose the acupuncture to do treatment, they still have the attitude of trust to the ancient art.

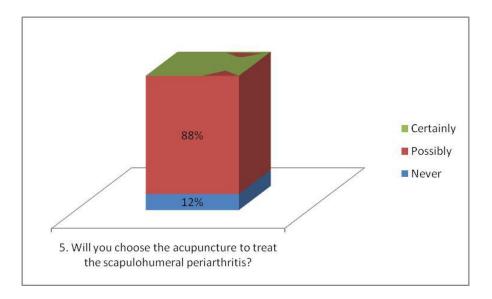


Chart 5-4 Choose the acupuncture to treat the scapulohumeral periarthritis.

The chart shows a significant proportion of students will choose the acupuncture to treat the scapulohumeral periarthritis. It means they believe acupuncture will relieve periarthritis of the shoulder.

Overall, the series of questions are prepared for the students, and it is a survey about the understanding of the acupuncture in the young generation. Most students have the curiosity about the knowledge of acupuncture and believe acupuncture has been used to alleviate certain diseases and do health-care.

Secondly, about understanding the knowledge of acupuncture in the application, it has three levels of comments. Table 5-1. Different numbers represent different levels of comments.

No	Not clearly	Yes
1	2	3

Table 5-1 Different levels of comments about the understanding of acupunctureknowledge in the application.

First of all, according to the responses from GSA students, Table 5-2 shows the results from eight students about the learning elements in the application.

A	В	С	D	Е	F	G	Н	Ι
	Q6	Q7	Q8	Q9	Q10	Q11	Q12	Q13
1	1	2	2	1	3	3	3	2
2	3	3	3	2	1	3	2	2
3	2	3	3	3	1	2	2	3
4	3	3	2	3	3	2	2	2
5	2	3	3	2	2	3	3	2
6	3	3	2	3	3	2	2	3
7	3	3	3	3	2	3	3	2
8	3	3	2	3	2	2	3	2
Average	2.5	2.875	2.5	2.5	2.125	2.5	2.5	2.25
STD	0.755929	0.353553	0.534522	0.755929	0.834523	0.534522	0.534522	0.46291

Table 5-2 The data statistics for the understanding of the knowledge in acupuncturefrom eight students.

Also, Chart 5-5 represents the mean values and standard deviation error bars for these eight questions which asked the participants to rate the learning results about the knowledge of acupuncture in the application.

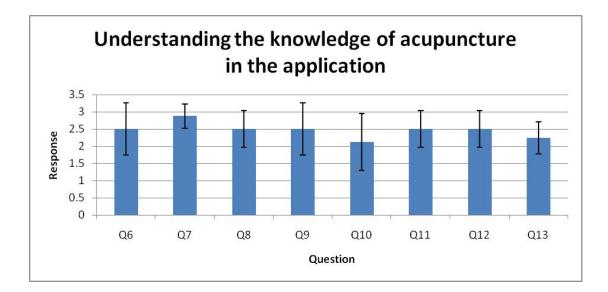


Chart 5-5 Mean value and error bars for questions testing the learning outcomes about the knowledge of acupuncture from eight students.

Moreover, Table 5-3 and Chart 5-6 show the results of the learning outcomes of the knowledge in acupuncture from the acupuncturists.

	Q6	Q7	Q8	Q9	Q10	Q11	Q12	Q13
1	2	3	3	2	2	3	3	2
2	3	3	2	3	2	3	3	3
Average	2.5	3	2.5	2.5	2	3	3	2.5
STD	0.707107	0	0.707107	0.707107	0. 57735	0	0	0.707107

Table 5-3 The data statistics for the understanding of the knowledge in acupuncturefrom two acupuncturists.

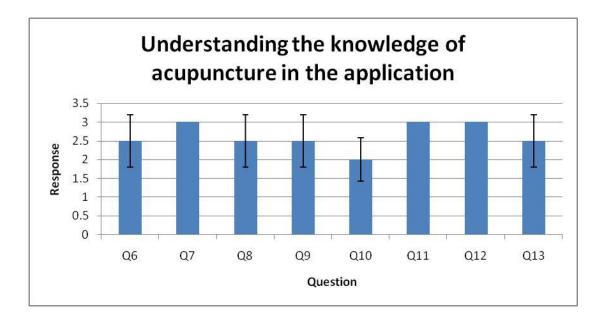


Chart 5-6 Mean value and error bars for questions testing the learning outcomes about the knowledge of acupuncture from two acupuncturists.

From these charts, participants comment the application can deliver the knowledge of acupuncture, except the effect of each acupoint (Question 10) is not very clear in the learning.

Thirdly, participants test the effective learning feedback of the acupuncture.

Strongly Disagree	Disagree	Neutral	Agree	Strongly Agree
1	2	3	4	5

In the chart, the number indicates the different level of agreement. Table 5-4

Table 5-4 shows the number means different level of agreement.

In this part, eight students implement the standard questionnaires (Questions 14-21), and the acupuncturists are asked the professional surveys (Question 14-23). Table 5-5 shows the data analysis of the accurate feedback system of acupuncture training from the total participants. Chart 5-7 shows the mean value and error bars about the participants' comments.

	Q14	Q15	Q16	Q17	Q18	Q19	Q20	Q21	Q22	Q23
1	3	3	2	3	3	5	3	3		
2	5	3	3	3	3	4	3	4		
3	4	2	2	2	3	3	2	4		
4	5	4	3	2	2	4	4	4		
5	4	4	2	2	3	4	4	4		
6	4	4	2	3	2	4	4	5		
7	4	3	3	3	3	4	3	4		
8	4	4	3	3	2	4	4	5		
9_expert	5	4	3	2	3	4	4	4	4	4
10_expert	4	4	3	3	3	5	4	4	3	4
Average	4.2	3.5	2.6	2.6	2.7	4.1	3.5	4.1	3.5	4
STD	0.632456	0.707107	0.516398	0.516398	0.483046	0.567646	0.707107	0.567646	0.707107	0

Table 5-5 The data analysis of the accurate feedback system.

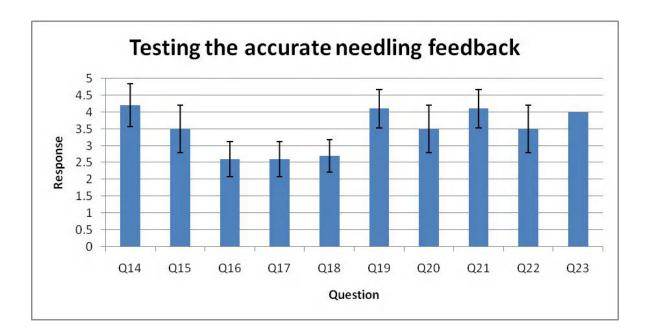


Chart 5-7 Mean value and error bars about the comments of needling feedback system.

According to the above charts, the information feedback about the weakness of the feedback in the angel of needling (Q 16), the depth of needling (Q17) and the force of needling (Q 18). In the Q16, $\bar{x} = 2.6$, $\sigma = 0.51$; in the Q17, $\bar{x} = 2.6$, $\sigma = 0.51$; in the Q18, $\bar{x} = 2.7$, $\sigma = 0.48$. It means in these three aspects, and the comments level is in the middle. Calibration of the feedback system is essential in the further development.

Fourthly, participants evaluate the immersion and visualisation in the virtual environment (Questions 22-26 in students' questionnaires or Questions 24-28 in acupuncturists' questionnaires).

	Q22	Q23	Q24	Q25	Q26
1	3	2	3	5	2
2	3	4	4	4	3
3	4	4	3	5	2
4	4	2	3	5	3
5	3	4	4	4	4
6	3	4	3	4	2
7	3	2	5	4	3
8	4	3	3	4	4
9_expert	4	3	3	5	3
10_expert	4	4	4	4	4
Average	3.5	3.2	3.5	4.4	3
STD	0.527046	0.918937	0.707107	0.516398	0.816497

Table 5-6 The data statistics about the comments in the feeling of the virtual environment.

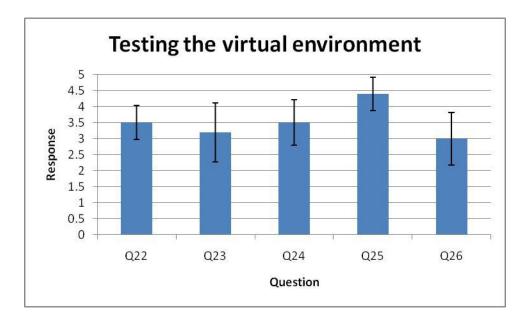


Chart 5-8 Mean value and error bars about the comments of immersion and visualization.

Fifthly, the evaluation of the application from participants (Questions 27-29 in students' questionnaires or Questions 29-31 in acupuncturists' questionnaires).

•

	Q27	Q28	Q29
1	4	3	4
2	5	4	4
3	4	3	5
4	5	4	5
5	5	4	5
6	4	4	4
7	5	4	5
8	5	3	5
9_expert	4	4	5
10_expert	5	4	5
Average	4.6	3.7	4.7
STD	0.516398	0.483046	0.483046

Table 5-7 The data statistics about the comments of the application.

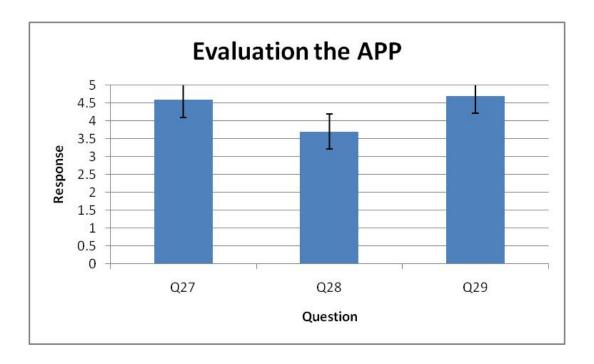


Chart 5-9 Mean value and error bars about the comments of the application.

5.3.3 Results of Evaluation

The vital purpose of testing the application is inviting the professional acupuncturists to provide the practical feedback from the experienced operation. Making an accurate acupuncture feedback platform is the topic of the application. Thus the precision of the realistic feedback in acupuncture is the essential requirement.

From the testing and data analysis, the results of the evaluation can be shown the below.

1. For the young students, acupuncture is an unfamiliar field, the most of them never went to see the professional acupuncturists before, and they did not understand the knowledge of acupuncture, thus, in this situation, delivering the understanding of acupuncture to the youth is a subject worth exploring.

2. Form the Charts 5-10 and 5-12, participants comment that the application can help them learn the knowledge of acupuncture in the process of operation, but the detailed knowledge is not highlighted and transparent, such as the effect of each acupoint (`x = 2, $\sigma = 0.57$).

3. In the testing of the accuracy of acupuncture feedback, acupuncturists rate the method of standardizing feedback highly. However, the precision needs to calibrate further.

4. The interaction in the virtual environment and the usefulness of the application have a favorable reception (Q25 `x =4.4 , σ = 0.51, Q28 `x = 3.7, σ = 0.48). Also, all participants comment the application is a breakthrough in the method of learning and training acupuncture (Q29 `x = 4.7, σ = 0.48).

5.4 Conclusion of Evaluation

Firstly, the acupuncturists have already refined the parameter of haptic device close to the practical needling. However, due to a large amount of variation between every patient, it is hard to set the feedback parameter accurately. In other words, the accurate feedback for each step of needling is impossible.

Secondly, the information about acupuncture and anatomy will be checked to deliver the rationale and knowledge of acupuncture effectively and correctly by the acupuncturists.

Thirdly, the students evaluate the application as an appropriate learning tool. It can spread the information and theory of acupuncture to the young generation logically and visually. Nearly every participant thinks the APP is a new teaching attempt to explore transmitting the acupuncture and exercising the needling. However, the weakness of the application is also mentioned in the testing, such as the occlusion problem between multiple interfaces.

To conclude, the acupuncturists comment that the application can be adapted to beginning teaching for the acupuncture. It is an important method to make the beginner understand the position of acupoint and experience the haptic feedback. Moreover, the virtual training also can prepare the real professional needling. However, because the treatment of acupuncture is connecting with the patients' feeling strictly, the virtual needling training cannot replace the actual exercising.

6 Discussion and Conclusion

6.1 Discussions

6.1.1 Discussion of Development Process

The process of developing the application has a most successful outcome. Overall, the development process can be divided into the following steps.

1. Set the acupuncture topic, and draw the storyboard to do the brainstorm. It is a useful method to make the design idea logically.

2. Functional designing. The application needs to be implemented by various functions. In the project, the primary functions are achieving the interaction in the virtual environment and learning to understand and script the Haptic Plugin.

3. Make the prototype of the application. The prototype includes establishing the virtual environment and scripting the interaction and functions.

4. Combine the HTC Vive and haptic device to develop the application further.

Furthermore, some questions are still confused me in the development, firstly, the haptic camera and VR camera cannot arrange synchronously, so the virtual environment sometimes will change and rotate the position. It means if I turn a PC to run the application, I will re-fix the total environment again possibly. Secondly, the controller of HTC Vive and the haptic device need to be used in the same application, and sometimes when the user immerses in the virtual environment, he or she can not find the haptic device through the VR headset. These are the hardware and developing problems, which can be improved in the future refinement.

6.1.2 Discussion of Immersion

Generally speaking, for immersion in the virtual environment, participants comment

that they feel present in the virtual environment. The acupuncturists also think the virtual environment can cultivate an ability of the hand-eye coordination, and the ability is essential for the medical students. Therefore, the immersion provides a potential method to train the students.

Moreover, the testers also find the audio system can help them immersing better - a method for establishing the training environment. The audio introduction can attract them to pay attention to the information in the process of training.

However, it still has some problems with the immersion. Firstly, the feedback system is the core function to make an accurate needling platform. The results of the concurrent and terminal feedback will be shown on Canvas, and it will generate the numerous interfaces. The multiple interacted interfaces can occlude the sight line of the testers partly. Therefore, the re-organizing of the interface in the virtual environment is a modified part of the application. Secondly, two participants meet the breaking off bug in the haptic plugin, that is the problem to break the immersion. The participants can not experience the application smoothly. Furthermore, the haptic device is lost in the virtual environment (when wearing the VR headset), it means changing the equipment from the controller to the haptics is difficult in the virtual environment.

6.1.3 Discussion of Potential for Learning

Overall, as a learning tool, the students and acupuncturists all think the application will aid their learning. It can be discussed in the following parts.

Firstly, considering the immersion of the virtual environment, it will help the user establish a visualization learning environment. The user will be like to reflect in the realistic setting and experience the training adequately. Besides, the user will experience the friendly and comfortable interaction in the virtual environment. The synthetic world is not static but responds to the user's input (gesture, verbal command, etc.). It defines a key feature of virtual reality, which is real-time interactivity (Grigore C. Burdea, 2003). In the application, the user can respond to the different inputs to achieve real-time interactivity. Furthermore, the environment also will provide an interacted feedback to the user, such as the animation about the result of choosing needles.

Secondly, all participants agreed the application can be used to deliver the knowledge of acupuncture and anatomy. On the one hand, the App will spread the knowledge to the students without significant foundation by the vivid and visual introduction video and the anatomical animation. On the other hand, the application explains the acupuncture knowledge, it is useful for the beginners of the acupuncture. The application can be used as a universal learning product, as well as a professional acupuncture training tool, because of the direct information communication and feedback.

Thirdly, combining with the virtual display, the haptic technology can be used for people to train some skills, which need the hand-eye coordination (Maharashtra, 2015). The training of acupuncture needs to improve the ability of the hand-eye coordination, so the application for making the haptic feedback platform is meaningful. The acupuncturists comment that although the parameter of the feedback is not quite accurate, the App has already come up with the effective training methods, and the measuring standard of the needling feedback. It will serve as a basis to consummate the perfect feedback platform in the training of acupuncture.

To conclude, the application can not only help to deliver the knowledge of acupuncture to the youth no educational limited, but also make the first acupuncture students train the needling.

6.2 Limitations

6.2.1 Suggestions by the Students and Acupuncturists

Suggestions by the Students and Acupuncturists

The acupuncturists focus on each feedback for the needling, they think the angle of needling is uncontrollable and inflexible, and the depth of needling needs to label it more clearly. Besides, the students comment that the multi-layer interface needs to be optimized better.

6.2.2 Technology Limitations

1. The breaking off bug in the haptic plugin when running the application.

2. The haptic camera and VR camera cannot arrange synchronously, so the virtual environment sometimes will change and rotate the position. It means if I turn a PC to run the application, I will re-fix the total environment again possibly.

6.3 Conclusion

The study has provided an application prototype for making an accurate acupuncture feedback platform in the virtual teaching environment. Combining with the VR and Phantom Omni, the application has the feature of immersion and real-time feedback, and it is proved to provide the more beneficial teaching and training environment.

The study improved the development of the haptic feedback skills, the usefulness for delivering the rationale and knowledge of acupuncture and anatomy to the next generation and the training feedback of the application has been proved effective and meaningful for the acupuncture students in the early stage of learning.

The application establishes the knowledge introduction interface, which can help the user with little acupuncture knowledge understand the knowledge of acupuncture through vivid and interacted images, or make the beginners of the acupuncture learn the acupuncture and anatomical knowledge point systematically. And this outcome is proved eminent through the testing.

The development of the application has allowed for the professional acupuncturists' simulation operation of the periarthritis of shoulder. Although the application has the disadvantage now, the suggestions from the professional acupuncturists are important for the implementing in the future development.

Overall, the acupuncturists think the application is essential for effective teaching and training for acupuncture. For the acupuncture students, it provides a simulated needling training repeatedly. For the professional acupuncturists, it offers an opportunity to plan the acupuncture operation before the actual needling. The

delivering of the knowledge in the acupuncture, and the measuring standard of the acupuncture feedback are rated highly, but the accuracy of needling needs to be realistic. Finally, the hardware limitations sometimes can reduce the smoothness and immersion of the application.

6.4 Future Development

Firstly, form the comments in the evaluation, because of the individual difference, the parameter of feedback in the acupuncture training is not accurate, it is an estimated value from the experiences of acupuncturists. The application is a prototype to establish the feedback platform in virtual acupuncture teaching and training. Thus, connecting with the right feedback database could improve the accuracy of acupuncture, and achieve the definite feeling from penetrating different tissues.

Furthermore, the application could have the acupuncture operation data integrated at any point. It would allow the users to train the latest operation repeatedly, reducing any risks posed by the actual training. Also, at the last step of the application, if the recorded operation results could be emailed to the professional acupuncturists veritably, the students will exercise the acupuncture operation in the absence of acupuncturists.

In the future, further testing can also help improve and verify the further development of the application. The prototype has been developed successfully, and the application has the potential to include more accurate feedback system, and the overall and latest training operation modes.

Reference

Biocca, F., 1992. Communication Within Virtual Reality: Creating a Space for Research. Journal of Communication. 42-4. 5-22. Available at: http://www.mindlab.org/images/d/DOC687.pdf [Accessed 2006]

Basdogan, C., Srinivasan, M.A., 2001. *Virtual environments for medical training: graphical and haptic simulation of laparoscopic common bile duct exploration. IEEE/ASME Transactions on Mechatronics*. 269-285. DOI: 10.1109/3516.951365

Bradley, P., 2006. *The history of simulation in medical education and possible future directions. Medical Education.* 40:254-262. DOI: 10.111/J.1365-2929.2006.02394.x

Byrne. C.M., 1993. Virtual Reality and education. Chapter 9 - Summer Students in Virtual Reality: A Pilot Study on Educational Applications of Virtual Reality Technology. Available at:

https://www.sciencedirect.com/science/article/pii/B9780127450452500192 [Accessed 1993]

Burdea, G., Coiffet, P., 2003. *Virtual Reality Technology.* 2th ed. Wiley-IEEE Press. 464. Available at:

https://www.wiley.com [Accessed 2003]

Claude, G., 2005. *Encyclopedia of Human Computer Interaction*. London: Idea Group Reference, 17033. Available at: <u>http://www.eurospanonline.com</u> [Accessed 2006]

Coles, T.R., Meglan, D., John, N.W., 2011. *The Role of Haptics in Medical Training Simulator:A Survey of the State of the Art. IEEE Consumer Electronics Society. IEEE Computer Society. IEEE Robotics & Automation Society.* 51-66. DOI: 10.1109/TOH.2010.19

Deshpanda, C.S., 2015. The Study of Haptics in Medical Training Simulation. International Journal of Advanced Research in Computer Engineering & Technology (IJARCET). 4-5. Available at:

http://ijarcet.org/wp-content/uploads/IJARCET-VOL-4-ISSUE-5-2488-2491.pdf

[Accessed 2015]

Eisenberg, D., Kaptchuk, J., et al., 2002. *Acupuncture: Theory, Efficacy, and Practice*. 136: 374-383. Available at:

http://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.886.5313&rep=rep1&type= pdf [Accessed 2002]

Hannaford, B., Okamura, A.M., 2008. *Haptics. Springer Handbook of Robotics.* 719-739. DOI 10.1007/978-3-540-30301-5_31

Hoffman, H.M., et al., 1995. *Virtual Reality Meets Medical Education*. Netherlands: IOS Press.130. Available at:

https://books.google.co.uk/books [Accessed 1995]

Han, H., Wang, P., Chen, X., Gao, X., 2016. *Learning method of self-evaluation and mutual-evaluation for practical teaching of Acupuncture and Moxibustion Technique curriculum: application and exploration*. 36(8). 877-879. DOI: 10.13703/j.02555-2930.2016.08.027

Heng P.A., Wong, T.T., et al., 2006. A Haptic Needle Manipulation Simulator for Chinese Acupuncture Learning and Training. International Journal of Image and Graphics. 205-230

Heng P.A., Wong, T.T., et al., 2006. Intelligent Inferencing and Haptic Simulation for Chinese Acupuncture Learning and Training. IEEE TRANSACTIONS ON INFORMATION TECHNOLOGY IN BIOMEDICINE. 10-1

Jung, Eun-Young., Park, D.K., Lee, Y.H., et al., 2011. *Evaluation of practical exercises using an intravenous simulator incorporating virtual reality and haptics device technologies. Nurse Education Today.* 32-4. 458-463

Jiang, Y.C., Jiang, J., et al., 2016. *Virtual reality of acupuncture manipulation in digital virtual human. Chinese Journal of Tissue Engineering Research.* 20(44):6643-6648.DOI: 10.3969/j.issn.2095-4344.2016.44.015

Kong, Jian., Gollub, R., Huang, T., et al., 2007. *Acupuncture De qi, from Qualitative History to Quantitative Measurement. The Journal of Alternative and Complementary Medicine*. 13-9. DOI: 10.1089/abm.2007.0524

Kuhn, C., Hubner, M., Krumm, H.G., et al., 2009. *The Karlsruhe Endoscopic Surgery Trainer as an example for virtual reality in medical education*. 122-125. DOI: 10.3109/13645709709152715

Laurel, B., Mountford, S.J., 1990. *The Art of Human-Computer Interface Design*. Available at:

https://dl.acm.org/citation.cfm?id=575201 [Accessed 2018]

Lee, I.S., Wallraven, C., et al., 2014. *Haptic Simulation for Acupuncture Needle Manipulation. THE JOURNAL OF ALTERNATIVE AND COMPLEMENTARY MEDICINE.* 654-660. DOI: 10.1089/acm.2013.0475

Massie, T.H., Salisbury, J.K., 1994. The PHANTOM Haptic Interface: A Device for *Probing Virtual Objects.* SensAble Technologies: ASME Paper. Available at: https://cn.3dsystems.com/scanners-haptics [Accessed 1994]

Ma, K., 2017. DECEMBER 2000 VOL 18. Acupuncture: Its Place in the History of Chinese Medicine. Available at: <u>http://aim.bmj.com/content/acupmed/18/2/88.full.pdf?sid=5aed504f-2d26-4b25-9c6f-0a8bcfb779bb</u> [Accessed 16 Sep 2017]

Mazuryk, T., Gervautz, M., 1999. *Virtual Reality History, Application, Technology and Future.* Available at:

https://www.researchgate.net/publication [Accessed 1999]

Mousesette, C., 2012. Simple Haptics. Sketching Perspectives for the Design of Haptic Interactions. Available at: http://umu.diva-portal.org [Accessed 2012]

Smaldino, S.E., Russell J.D., Heinich, R., Molenda, M., 2008. *Instructional Technology and Media for Learning.* 12th ed. Available at: <u>https://www.pearsonhighered.com/assets/preface/0/1/3/4/0134287487.pdf</u>

Steuer, J., 1992. *Defining Virtual Reality: Dimensions Determining Telepresence*. Journal of Communication. 42,4. 73

Siciliano, B., Khatib, O., 2016. Springer Handbook of Robotics. 2th ed. Springer Nature. DOI: 10.1007/978-3-319-32552-1

Sherman, W.R., Craig, A.B., 2002. Understanding Virtual Reality: Interface, Application, and Design. Available at: www.mkp.com [Accessed 2002]

Tsuei J.J., 1996. The sciences of acupuncture-theory and practice. IEEE Engineering in Medicine and Biology Society. 52-57. DOI: 10.1109/51.499758

Appendix 1 - Questionnaires

Participant Questionnaire:

* Only the professional acupuncturist received this document

Making a Haptic Acupuncture Teaching Platform in Virtual Reality MSc in Serious Games and Virtual Reality Researcher: Boyu Xu

The questionnaire is designed to test the content and usefulness of the application. This includes validating the operation and visualisation of the application, and evaluation it. You will put forward the suggestions to improve the further development of the application.

You will be asked questions about the following 4 areas.

- 1. Understanding the knowledge of acupuncture.
- 2. Testing the accurate operation feedback of acupuncture.
- 3. Testing the immersion and visualisation in the virtual environment.
- 4. Further development of the application in the virtual environment.

Understanding the knowledge of acupuncture

Please circle below if any of the following elements you find them in the application:For example:YesNoNot clearly

6.The concept of acupuncture.

Yes No Not clearly

7.The concept of scapulohumeral periarthritis.

Yes No Not clearly

8. The concept of main meridian channels.

Yes No Not clearly

9. The position of each acupoint.

Yes No Not clearly

10. The effect of each acupoint.

Yes No Not clearly

11. The hint of acupuncture operation.

Yes No Not clearly

12.The knowledge of anatomy.

Yes No Not clearly

13. The relationship between anatomy and acupuncture.

Yes	No	Not clearly

Other comments:

Testing the effective learning feedback of acupuncture

Please circle below if you agree it.

14.You could achieve a clear feedback about the type of needles.										
Strongly disagree	Disagree	Neutral	Agree	Strongly agree						
15.You could achieve a	15.You could achieve a clear feedback about the position of the acupoint.									
Strongly disagree	Disagree	Neutral	Agree	Strongly agree						
16.You could achieve a	a clear feedback	about the ang	le of needling.							
Strongly disagree	Disagree	Neutral	Agree	Strongly agree						
17.You could achieve a	a clear feedback	of the depth c	of needling.							
Strongly disagree	Disagree	Neutral	Agree	Strongly agree						
18.You could achieve a	a clear feedback	of the force o	f needling.							
Strongly disagree	Disagree	Neutral	Agree	Strongly agree						
19.You could record the	he accurate op	eration each st	ep.							
Strongly disagree	Disagree	Neutral	Agree	Strongly agree						
20.You could achieve a clear evaluation of each acupoint.										
Strongly disagree	Disagree	Neutral	Agree	Strongly agree						

21.You could achieve a clear evaluation of the whole operation training.

Strongly disagree	Disagree	Neutral	Agree	Strongly agree					
22.You could learn th	22.You could learn the accurate anatomical knowledge in the application.								
Strongly disagree	Disagree	Neutral	Agree	Strongly agree					
23.You could learn th	le accurate acu	puncture know	vledge in the a	application.					
Strongly disagree	Disagree	Neutral	Agree	Strongly agree					
Other comments:	Diougroo	Noutai	/ groo	outingly agree					
Testing the ir	nmersion and v	/isualisation ir	n the virtual e	nvironment					
Please circle below it									
24.You could feel co	mfortable and f	riendly in the p	process of testi	ng the application.					
Strongly disagree	Disagree	Neutral	Agree	Strongly agree					
25.The scale of obje	ects in the virtua	l environment a	are realistic.						
Strongly disagree	Disagree	Neutral	Agree	Strongly agree					
26.You feel you are i	n the virtual en	vironment.							
Strongly disagree	Disagree	Neutral	Agree	Strongly agree					
27.You feel you are n	naking the inter a	action with the	objects.						
Strongly disagree	Disagree	Neutral	Agree	Strongly agree					
28.You could run the	application smo	othly.							
Strongly disagree	Disag	ree	Neutral	Agree					
Strongly agree									
Other comments:									

The evaluation of the application

29.You could learn the	knowledge of ac	cupuncture an	d anatomy in	the application.
Strongly disagree	Disagree	Neutral	Agree	Strongly agree

30.You think the application is **useful** for students who want to learn the acupuncture operation to treat the scapulohumeral periarthritis

Strongly disagree Disagree Neutral Agree Strongly agree

31.You think the application is **a new try** in the teaching of learning and training acupuncture.

Strongly disagree Disagree Neutral Agree Strongly agree

Please answer the questions below to comment your thoughts. This will help to develop the application further before the submission date.

1. What did you like most about the application?

2. What did you dislike most about the application?

3. Were there any problems about the application?

4. Please write down the additional suggestions for further development.

Participant Questionnaire:

* Only the student received this document

Making a Haptic Acupuncture Teaching Platform in Virtual Reality MSc in Serious Games and Virtual Reality Researcher: Boyu Xu

The questionnaire is designed to test the content and usefulness of the application. This includes validating the operation and visualisation of the application, and evaluation it. You will put forward the suggestions to improve the further development of the application.

You will be asked questions about the following 5 areas.

- 1. People's understanding of acupuncture.
- 2. The knowledge of acupuncture in the application.
- 3. Testing the effective learning feedback of acupuncture.
- 4. Testing the immersion and visualisation in the virtual environment.
- 5. Further development of the application in the virtual environment.

People's understanding of acupuncture

Please circle below if you agree it.

For example: How often do you see the professional acupuncturist?							
Never	Rarely	Sometimes	Of	ten		Very often	
1. Do you un	derstand the o	concept of acupuncture	?				
None	A little	Ordinary		Mucl	٦	Hu	uge
2. How often	do you see th	e professional acupuno	cturist?				
Never	Rarely	Sometimes		C	Often		Very
often							
3. Why do yo	u see the prof	essional acupuncturist	?				
Have a fev	er	Massage	Body	pain	(like	shoulder	pain)
other							
4. Do you think the acupuncture is useful?							

Ridiculous Useless Sometimes useful Useful Really useful

5. Will you choose the acupuncture to treat the scapulohumeral periarthritis?

Possibly	Certainly
	Possibly

	Understandi	ng the k	nowledge	
Please circle be	low if any of the	e following	g elements	s
For example:	Yes	No	Not cle	arl
	. .			
6. The concept	-			
Yes	No	Not	clearly	
7. The concept	of scapulohum	eral peria	rthritis.	
Yes	No	Not	clearly	
8. The concept	of main meridia	in channe	els.	
Yes	No	Not	clearly	
	of each same in	- 4		
9. The position	-			
Yes	No	Not	clearly	
10. The effect c	of each acupoint	t.		
Yes	No	Not	clearly	
11. The hint of a	acupuncture op	eration.		
Yes	No		clearly	
12. The knowle	•			
Yes	No	Not	clearly	
13. The relation	iship between a	inatomy a	and acupu	ncture.
Yes	No	Not	clearly	
Other comments	S:			

Testing the effective learning feedback of acupuncture

Please circle below if you agree it.

14. You	could achieve a clear	feedback about the type	e of needles.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree	-		-
0,1	0			
15. You	could achieve a clear	feedback about the pos	ition of the acupoint.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree			
	-			
16. You	could achieve a clear	feedback about the ang	le of needling.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree			
17. You	could achieve a clear	feedback of the depth c	of needling.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree			
18. You	could achieve a clear	feedback of the force o	f needling.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree			
19. You	could record the acc	u rate operation each st	ep.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree			
20. You	could achieve a clear	evaluation of each acu	ipoint.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree			
21. You	could achieve a clear	evaluation of the whol	e operation training.	
Strongly	disagree	Disagree	Neutral	Agree
Strongly	agree			
Other co	mments:			

Testing the immersion and visualisation in the virtual environment

Please circle below if you agree it.

22. You could feel comfortable and friendly in the process of testing the application.					
Strongly disagree	Disagree	Neutral	Agree	Strongly agree	
23. The scale of object	ts in the virtual e	environment a	re realistic.		
Strongly disagree	Disagree	Neutral	Agree	Strongly agree	
24. You feel you are in	the virtual envi	ronment.			
Strongly disagree	Disagree	Neutral	Agree	Strongly agree	
25. You feel you are making the interaction with the objects.					
Strongly disagree	Disagree	Neutral	Agree	Strongly agree	
26. You could run the application smoothly.					
Strongly disagree	Disagree	Neutral	Agree	Strongly agree	
	-		-		
Other comments:					

The evaluation of the application

27. You could learn the knowledge of acupuncture and anatomy in the
application.Strongly disagreeDisagreeNeutralAgreeStrongly agree

28. You think the application is **useful** for students who want to learn the acupuncture operation to treat the scapulohumeral periarthritis

	Strongly disagree	Disagree	Neutral	Agree	Strongly agree
--	-------------------	----------	---------	-------	----------------

29. You think the application is **a new try** in the teaching of learning and training acupuncture.

Strongly disagree Disagree Neutral Agree Strongly agree

Please answer the questions below to comment your thoughts. This will help to develop the application further before the submission date.

1. What did you like most about the application?

5. What did you dislike most about the application?

6. Were there any problems about the application?

7. Please write down the additional suggestions for further development.

Appendix 2 - Introduction Video



Acupuncture Introduction.mp4.mp4